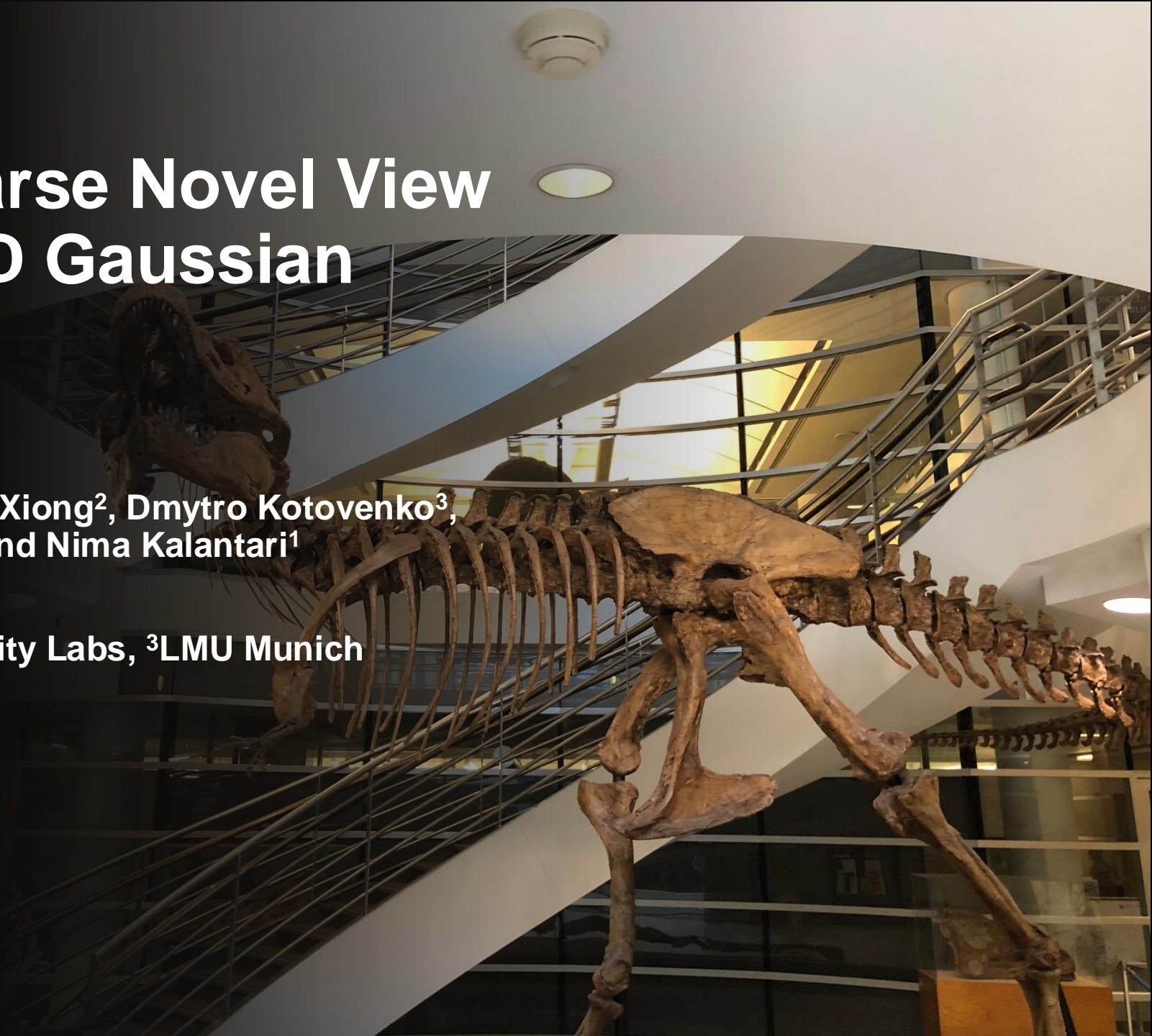


CoherentGS: Sparse Novel View Synthesis with 3D Gaussian Splatting

Avinash Paliwal^{1,2}, Wei Ye², Jinhui Xiong², Dmytro Kotovenko³,
Rakesh Ranjan², Vikas Chandra² and Nima Kalantari¹

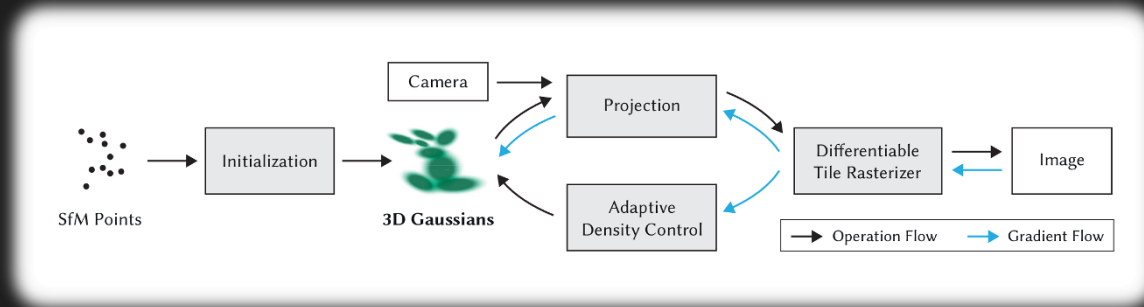
¹Texas A&M University, ²Meta Reality Labs, ³LMU Munich

ECCV 2024



Goal

3D Gaussian Splatting (3DGS)



[Kerbl et al. 2023]

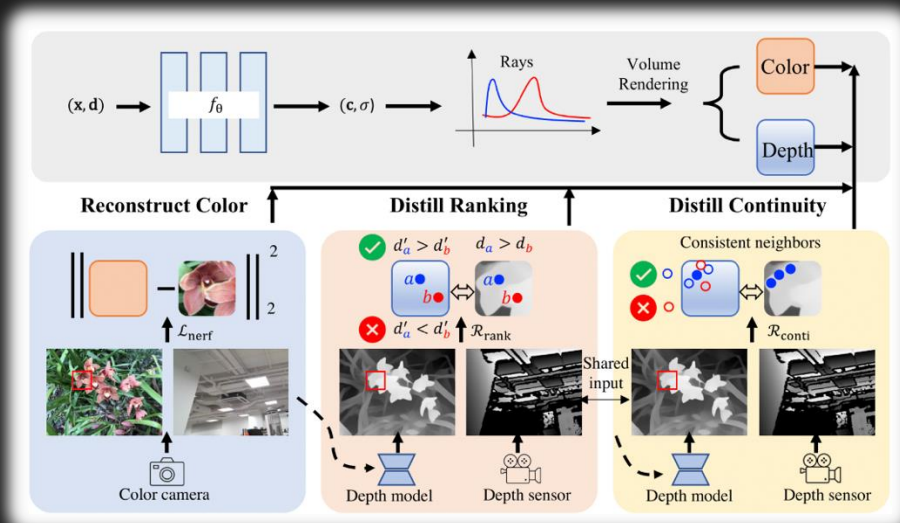
- Adapt 3DGS to extremely sparse input setting (2 – 4 images)



Ours

NeRF for Sparse Novel View Synthesis

Neural Radiance Field (NeRF)



[Wang et al. 2023, Yang et al. 2023, Seo et al. 2023, Kangle et al. 2021, Niemeyer et al. 2021]

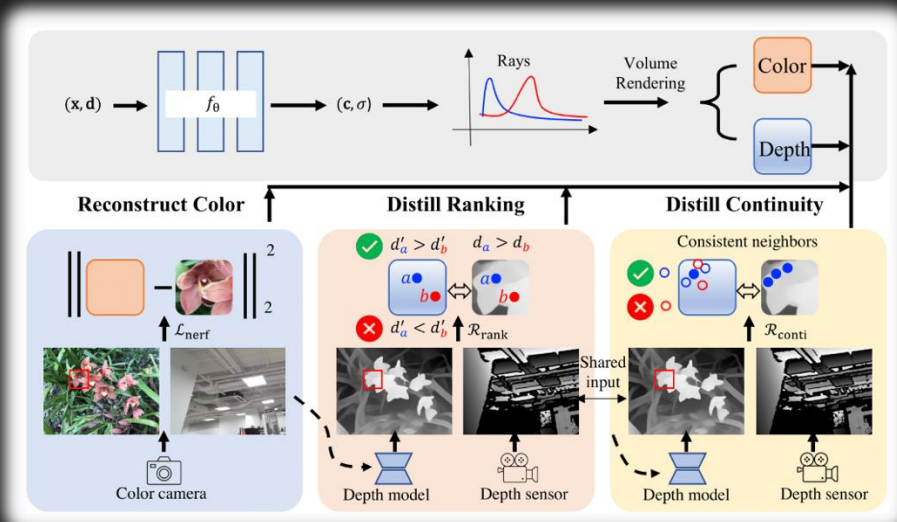
FreeNeRF [Yang et al. 2023]

➤ Additional regularizations to constrain the optimization

➤ Insufficient constraints for 2 to 4 inputs

NeRF for Sparse Novel View Synthesis

Neural Radiance Field (NeRF)

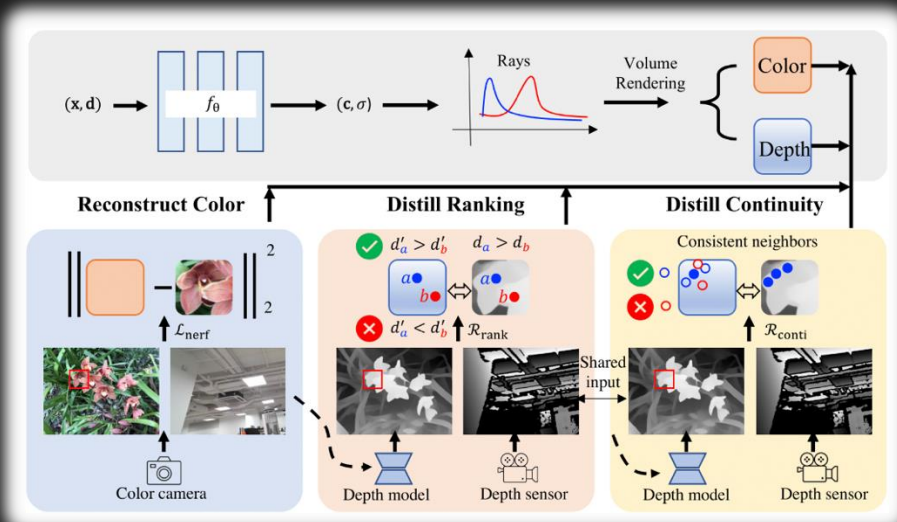


[Wang et al. 2023, Yang et al. 2023, Seo et al. 2023, Kangle et al. 2021, Niemeyer et al. 2021]

$$(x, y, z, \theta, \phi) \rightarrow \begin{matrix} \text{|||} \\ \text{|||} \\ \text{|||} \\ F_\Theta \end{matrix} \rightarrow (RGB\sigma)$$

NeRF for Sparse Novel View Synthesis

Neural Radiance Field (NeRF)

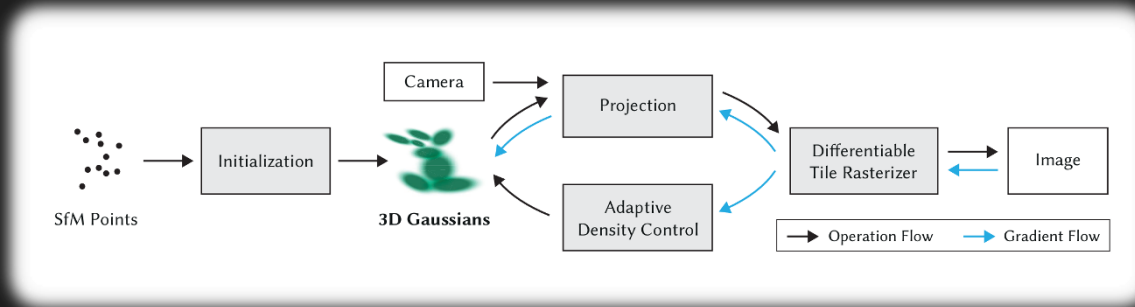


[Wang et al. 2023, Yang et al. 2023, Seo et al. 2023, Kangle et al. 2021, Niemeyer et al. 2021]

$$(x, y, z, \theta, \phi) \rightarrow \begin{matrix} \text{|||} \\ \text{|||} \\ \text{|||} \\ F_\Theta \end{matrix} \rightarrow (RGB\sigma)$$

3D Gaussian Splatting (3DGS)

3D Gaussian Splatting (3DGS)



[Kerbl et al. 2023]

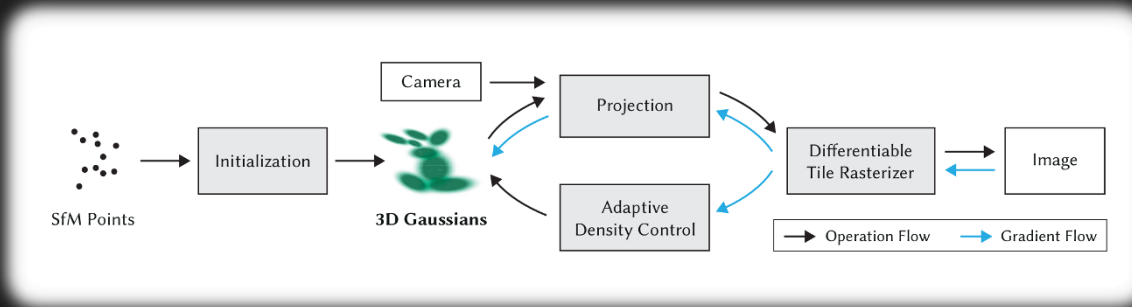


3DGS [Kerbl et al. 2023]

- Unstructured 3D representation
- Existing regularizations not as effective

Goal

3D Gaussian Splatting (3DGS)



[Kerbl et al. 2023]

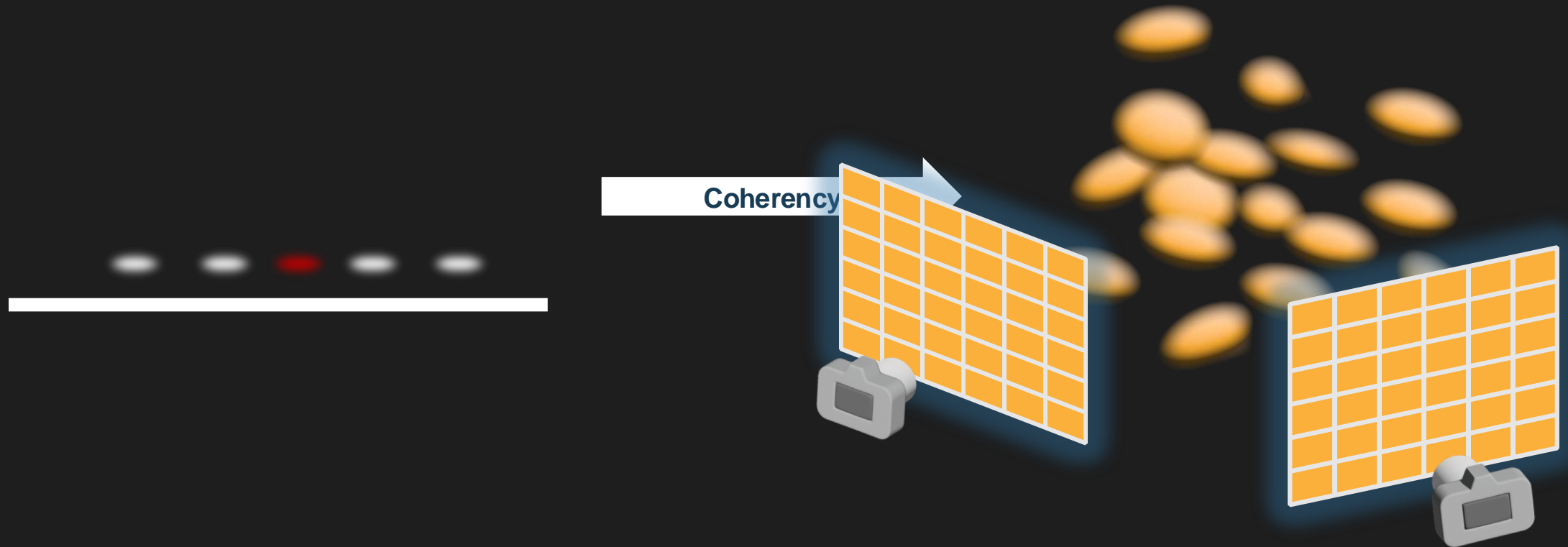
➤ Add coherency to the representation



3DGS [Kerbl et al. 2023]

Coherent Representation

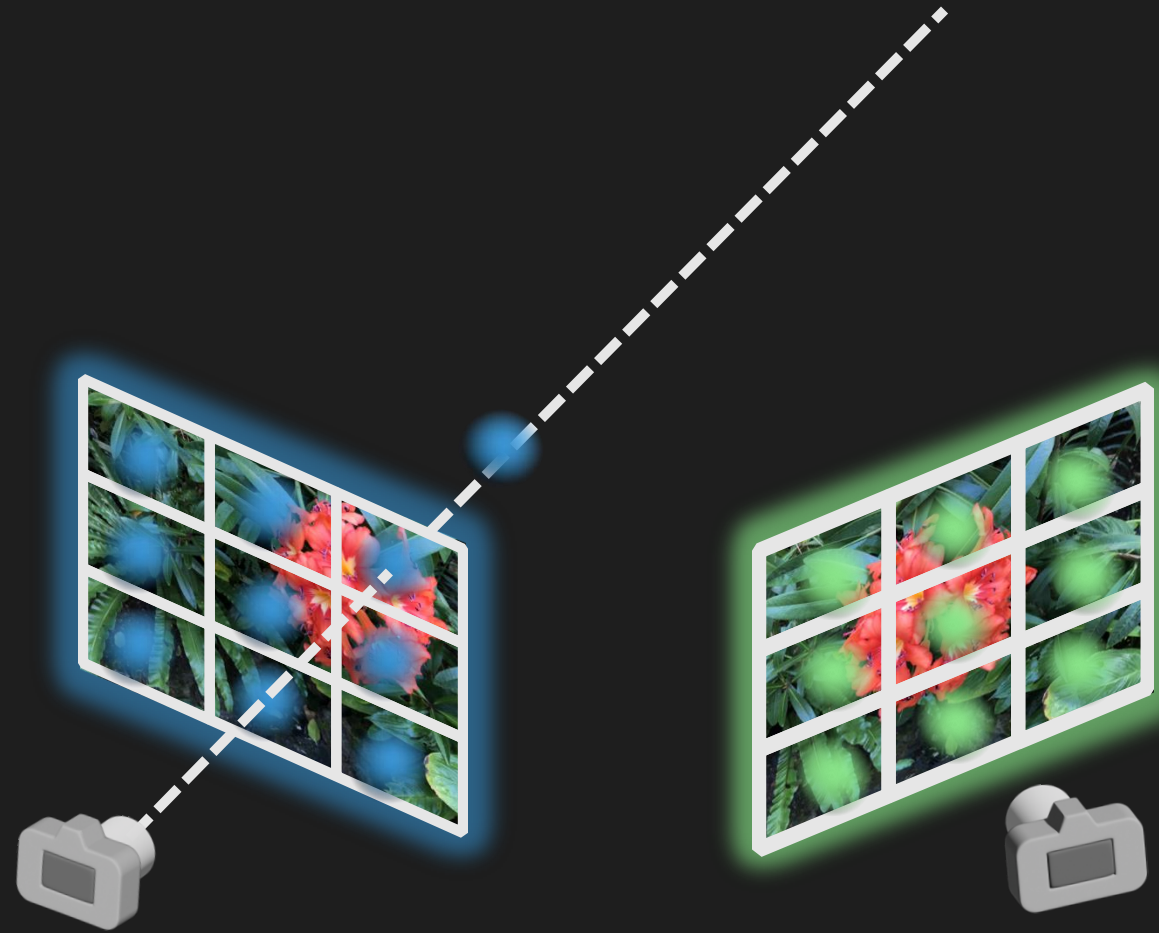
- Difficult to enforce in the unstructured representation
- Add coherency in 2D domain



Coherent Representation

- Coherency in 2D domain

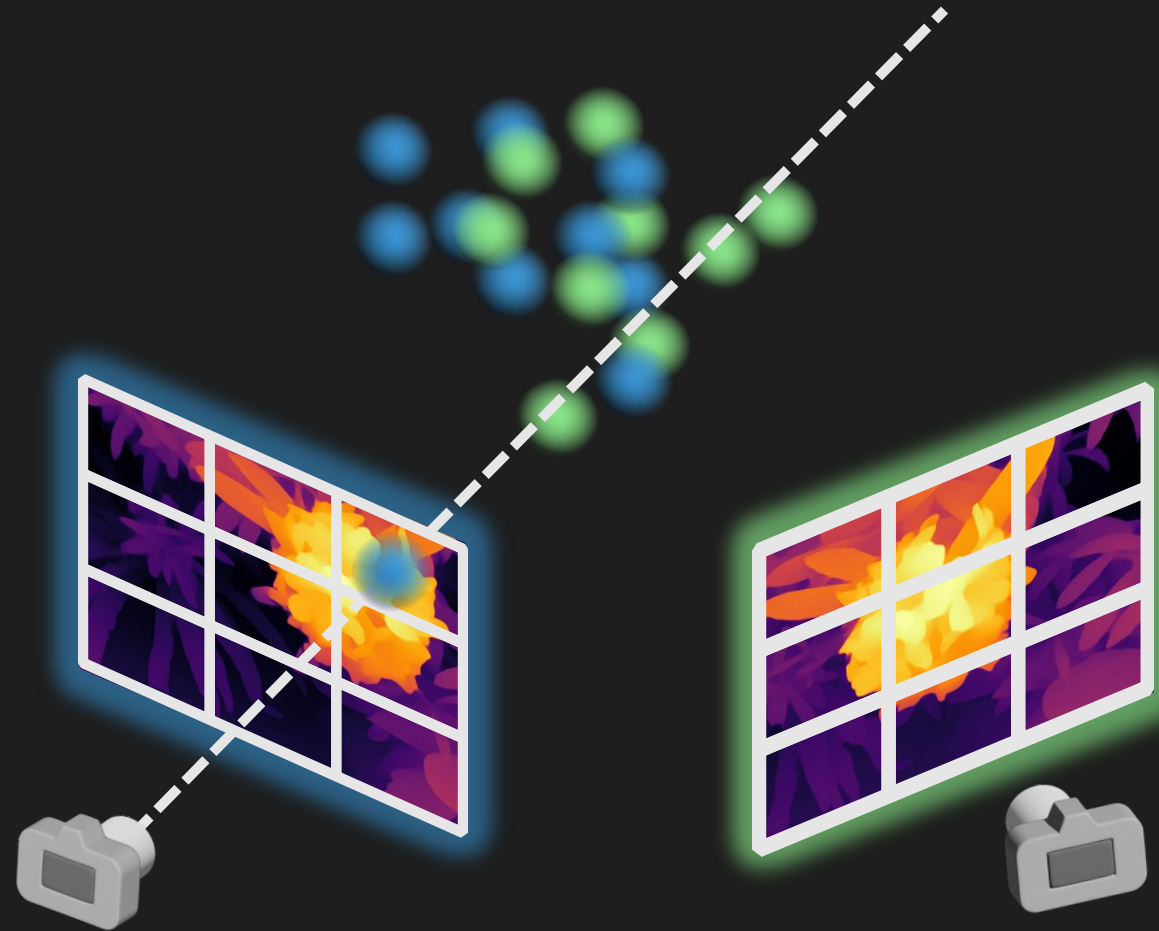
- One gaussian per pixel
- Gaussians move along camera ray



Coherent Representation

➤ Coherency in 2D domain

- One gaussian per pixel
- Gaussians move along camera ray
- Gaussian position controlled by pixel depth
- Enable regularizations in 2D

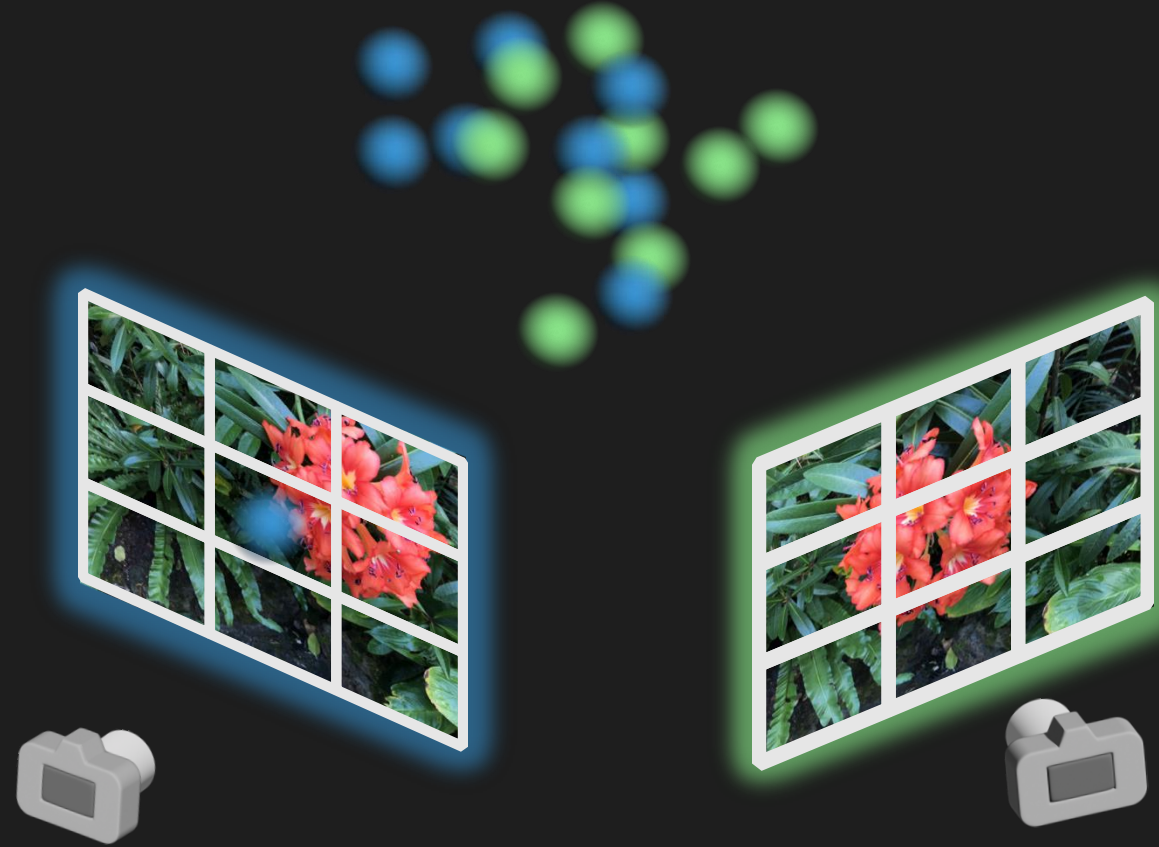


Constraints

- We add coherency to the 3D Gaussian representation
 - Single-view constraints
 - Multi-view constraints

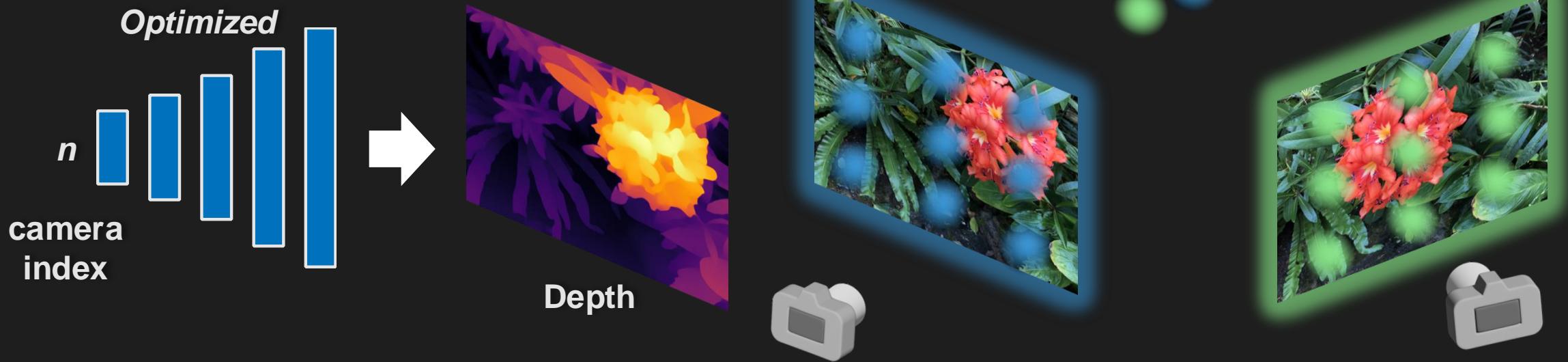
Single-view Constraints

➤ Coherency in 2D domain



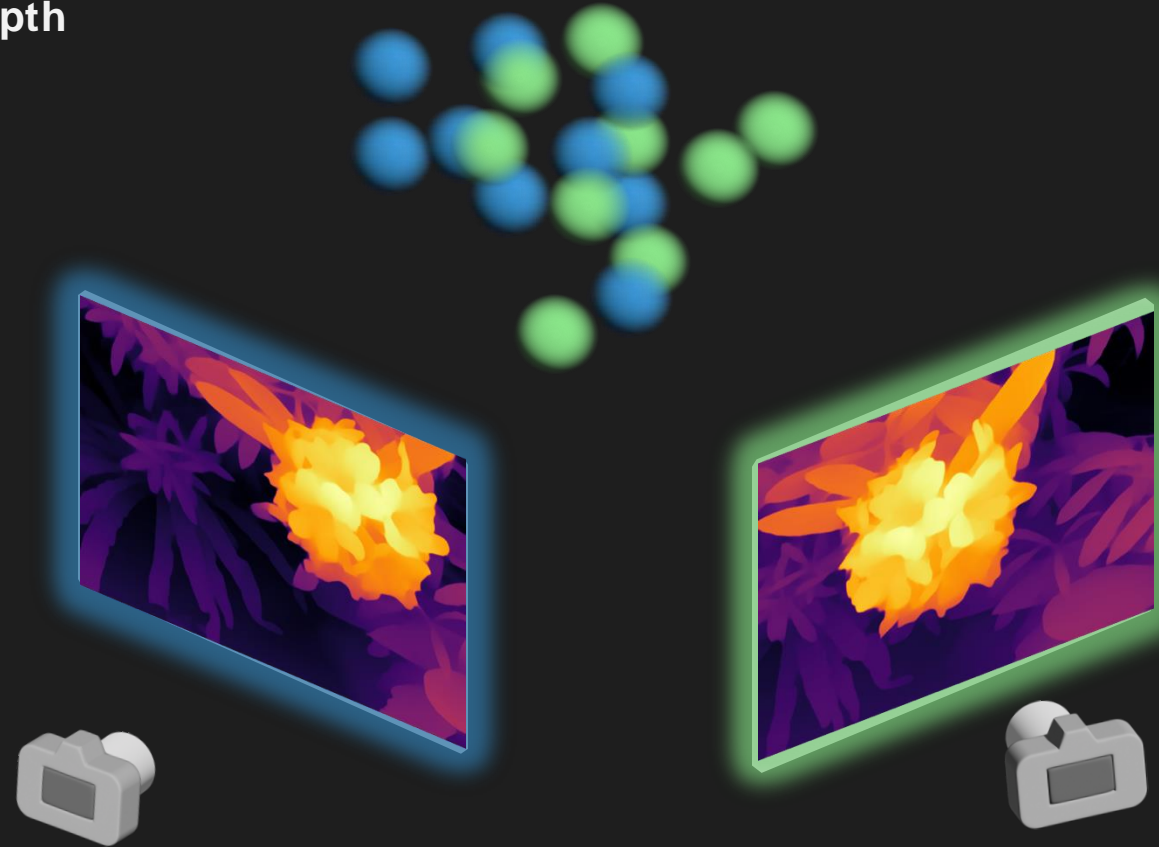
Single-view Constraints

- Coherency in 2D domain
 - Implicit decoder predicts smooth 2D depth
 - Gaussians move together as a group

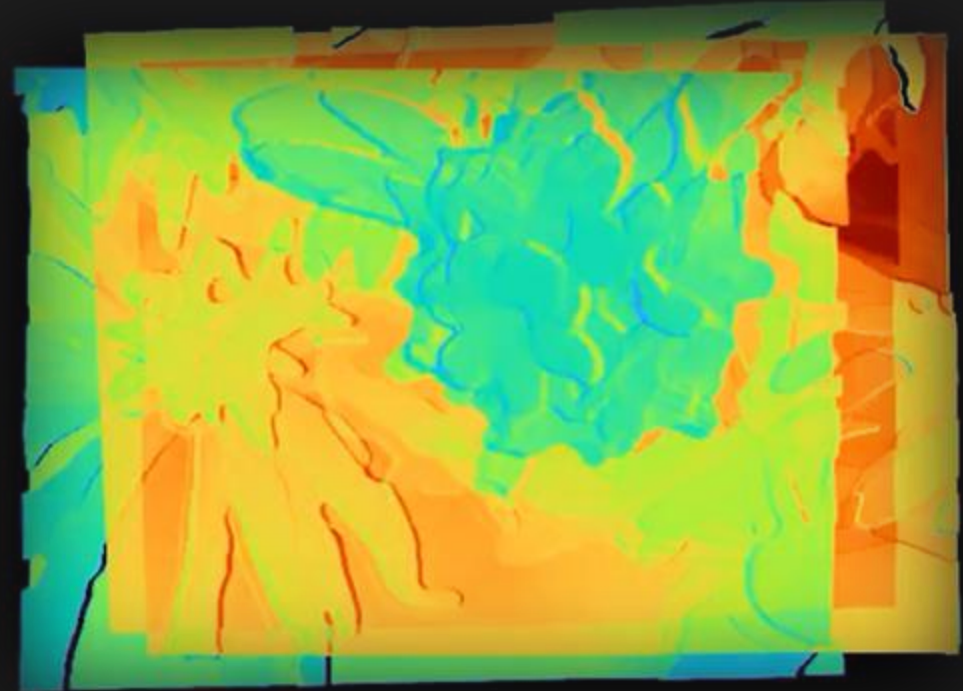


Multi-view Constraints

- Coherency in 2D domain
 - Rasterize **all the gaussians** to obtain scene depth
 - Apply total variation regularization



Optimization



- Gaussians from different views are quickly aligned due to coherent movement
- Obtain high quality geometry and texture without noisy gaussians

Inpainting Results – 3 inputs



Ours w/o inpainting



Ours w/ inpainting

Inpainting Results – 3 inputs



FreeNeRF [Yang et al. 2023]



SparseNeRF [Wang et al. 2023]



Ours w/o inpainting



Ours w/ inpainting

Results – 2 inputs



FlipNeRF [Seo et al. 2023]



SparseNeRF [Wang et al. 2023]



FreeNeRF [Yang et al. 2023]



Ours

Results – 3 inputs



FlipNeRF [Seo et al. 2023]



SparseNeRF [Wang et al. 2023]



FreeNeRF [Yang et al. 2023]



Ours

Thank You

Poster #319

Session: Thu 3 Oct 10:30 a.m. - 12:30 a.m.