Prompt-Driven Contrastive Learning for Transferable Adversarial Attacks



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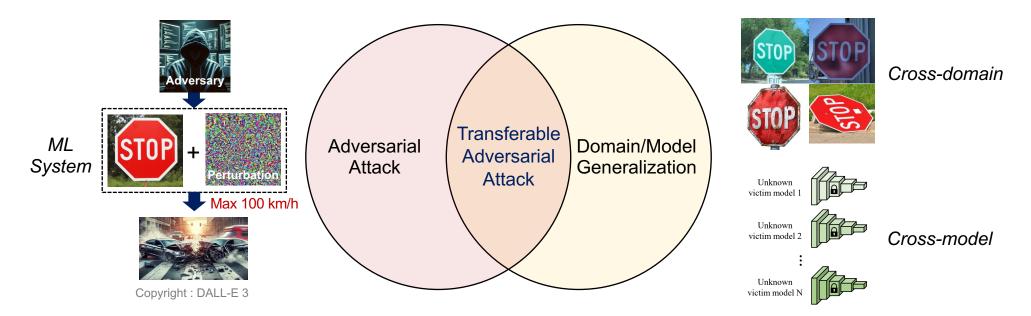


EUROPEAN CONFERENCE ON COMPUTER VISION

Introduction



- Transferable Adversarial Attacks
 - Crafting adversarial perturbations that are transferable to unknown domains and models.
- Significance
 - Security concerns: Identifying vulnerabilities in ML systems (e.g., autonomous driving)
 - Robustness testing: Serving as a benchmark for evaluating the ML robustness.

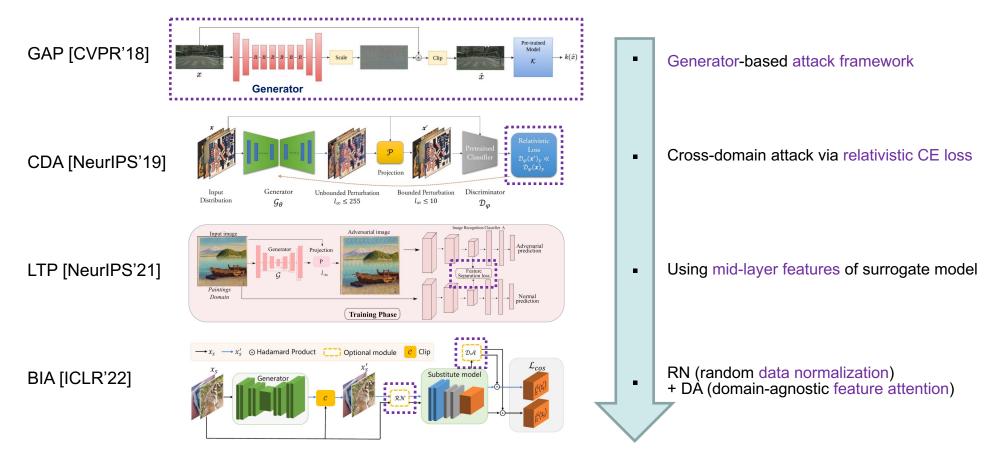


Prompt-Driven Contrastive Learning for Transferable Adversarial Attacks

Introduction



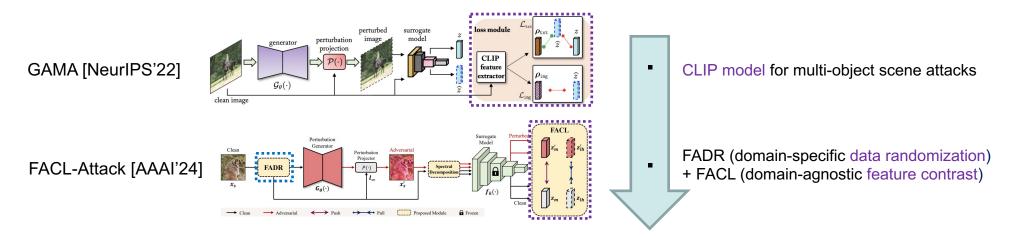
• Recent progress in generator-based transferable attacks (1/2)



Introduction



• Recent progress in generator-based transferable attacks (2/2)



• Key insights and our hypothesis

Identifying generalizable representations across diverse domains and models



Training a robust perturbation generator that is both domain- and model-agnostic

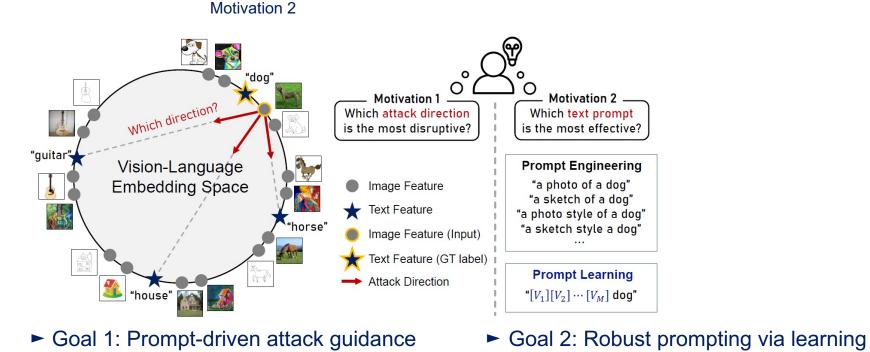
"Foundation model guidance could lead to more effective attacks."



- A new comer: CLIP
 - A vision-language foundation model with highly generalizable representations
 - In a joint vision-language space, <u>a single text can represent various images from diverse domains.</u>



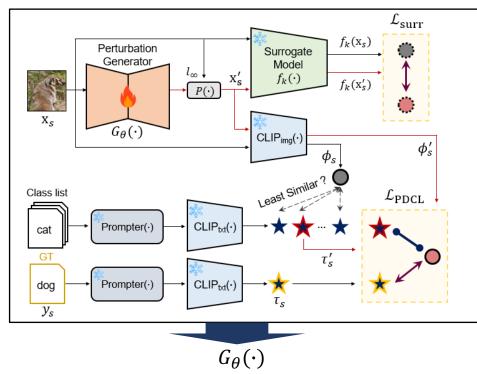
<u>The type of text prompt greatly affects the effectiveness</u>.

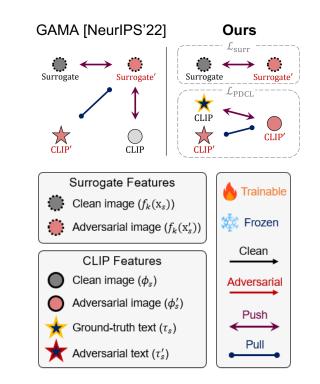


Proposed Method



- [Method 1] Prompt-driven attack guidance
 - Leveraging prototypical text features, our prompt-driven contrastive loss \mathcal{L}_{PDCL} improves the robustness of the perturbation generator $G_{\theta}(\cdot)$ to diverse input images.
 - Our loss separately deals with feature spaces of surrogate model and CLIP model.



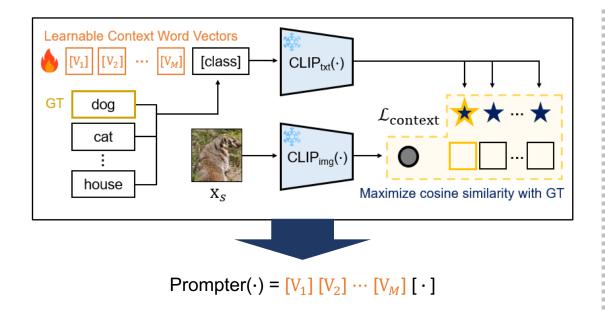


Proposed Method



[Method 2] Robust prompting via learning

- For effective prompt-driven feature guidance, we pre-train learnable context word vectors using $\mathcal{L}_{context}$ to produce more generalizable text features [Zhou et al., 2022].
 - With the frozen CLIP model, we train only the learnable context word vectors of Prompter(·).



Improving Robustness to Distribution Shiftsa photo of adogvs. $[V_1]$ $[V_2]$... $[V_M]$ doga photo of adogvs. $[V_1]$ $[V_2]$... $[V_M]$ doga photo of aa couracy (%)a couracy $[V_M]$ $[V_M]$ $[V_M]$ $[V_M]$ a photo of a $[V_M]$ $[V_M]$ $[V_M]$ $[V_M]$ $[V_M]$ a photo of a $[V_M]$ $[V_M]$ <td

Method	ImageNet-1K	-V2	-Sketch	-A	-R
Zero-shot CLIP [41]	66.7	60.9	46.1	47.8	74.0
$\mathrm{w}/ \; \mathtt{Prompter}(\cdot)$	71.9	64.2	46.3	48.9	74.6

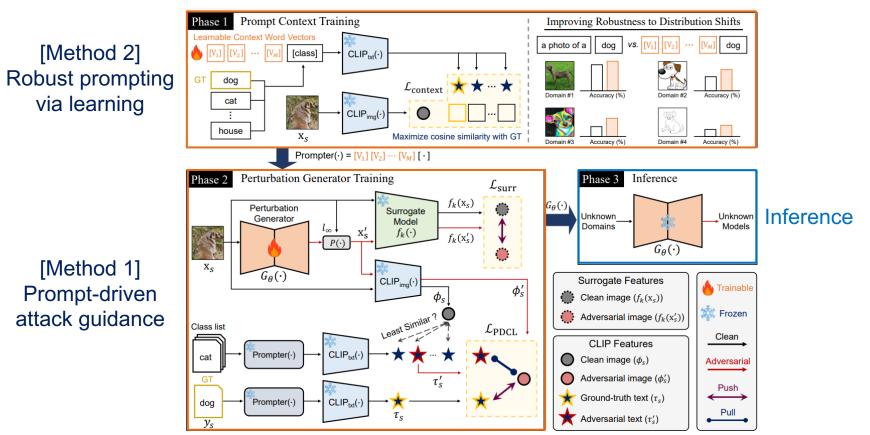
[Zhou et al., 2022] Learning to Prompt for Vision-Language Models, IJCV 2022

Proposed Method

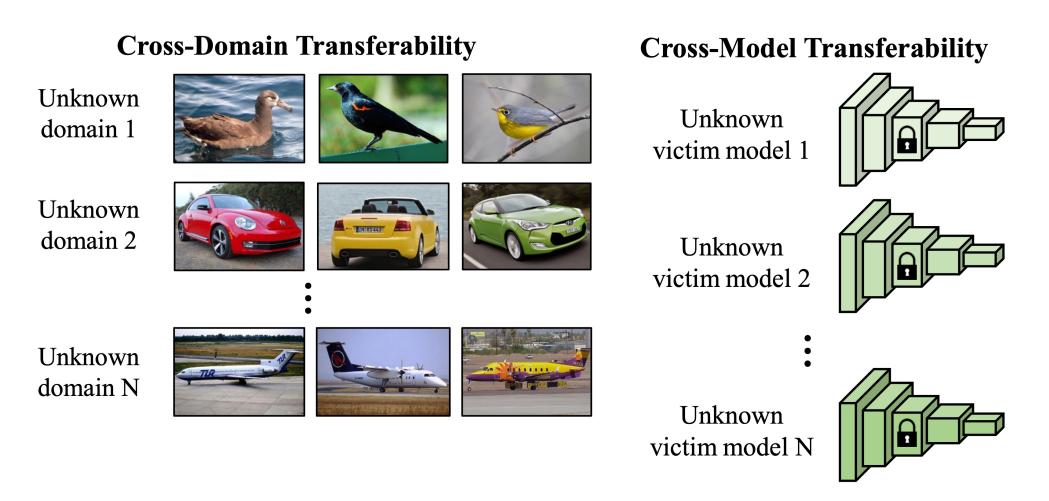


Overall framework

- Two training phases (Phase 1 & Phase 2) and an inference phase (Phase 3)









Cross-domain attack transferability

Method		CUB-200-2011			Stanford Cars			FGVC Aircraft		
	Res-50	SENet154	SE-Res101	Res-50	SENet154	SE-Res101	Res-50	SENet154	SE-Res101	- AVG.
Clean	87.33	86.81	86.59	94.25	93.35	92.96	92.14	92.05	91.84	90.81
GAP [40]	68.85	74.11	72.73	85.64	84.34	87.84	81.40	81.88	76.90	79.30
CDA [35]	69.69	62.51	71.00	75.94	72.45	84.64	71.53	58.33	63.39	69.94
LTP [34]	<u>30.86</u>	52.50	62.86	34.54	65.53	73.88	15.90	60.37	52.75	49.91
BIA [60]	32.74	52.99	58.04	39.61	69.90	70.17	28.92	60.31	46.92	51.07
GAMA [2]	34.47	54.02	57.66	<u>30.16</u>	69.80	<u>63.82</u>	25.29	58.42	43.41	<u>48.56</u>
Ours	22.97	49.19	54.92	22.58	64.95	63.70	15.81	53.83	47.25	43.91

- **Domain**: ImageNet-1K (Source Domain) → CUB, CAR, AIR (Target Domain)
- Model: VGG-16 (Surrogate Model) → Various Models (Victim Models)



Cross-model attack transferability

Method	Res-50	Res-152	Dense-121	Dense-169	Inc-v3	MNasNet	ViT-B/16	ViT-L/16	AVG.
Clean	74.61	77.34	74.22	75.75	76.19	66.49	79.56	80.86	75.63
GAP [40]	57.87	65.50	57.94	61.37	63.30	42.47	72.89	76.69	54.34
CDA [35]	36.27	51.05	38.89	42.67	54.02	33.10	68.73	74.22	53.24
LTP [34]	$\underline{21.70}$	39.88	23.42	25.46	41.27	45.28	72.44	76.75	43.28
BIA [60]	25.36	42.98	26.97	32.35	41.20	34.31	67.05	73.23	42.93
GAMA [2]	24.82	43.22	24.84	30.81	<u>35.10</u>	27.96	67.33	<u>73.16</u>	<u>40.91</u>
Ours	20.87	38.62	21.26	<u>29.01</u>	32.99	$\underline{28.00}$	65.53	72.52	38.60

Domain : ImageNet-1K (Source Domain = Target Domain)

• Model : VGG-16 (Surrogate Model) → Various Models (Victim Models)



• Ablation study on our proposed losses

Method	$\mathcal{L}_{ ext{surr}}$	$\mathcal{L}_{ ext{GAMA}}$	$\mathcal{L}_{ ext{PDCL}}$	$\mathcal{L}_{ ext{context}}$	Cross-Domain	Cross-Model
Clean	_	_	—		90.85	75.63
BIA [60]	\checkmark	_	_	_	51.07	42.93
GAMA [2]	\checkmark	\checkmark	—	—	48.56	40.91
\mathbf{Ours}^\dagger	\checkmark		\checkmark		46.69	40.35
Ours	\checkmark	—	\checkmark	\checkmark	43.91	38.60

• Our proposed \mathcal{L}_{PDCL} achieves SoTA even w/o prompt learning of $\mathcal{L}_{context}$.



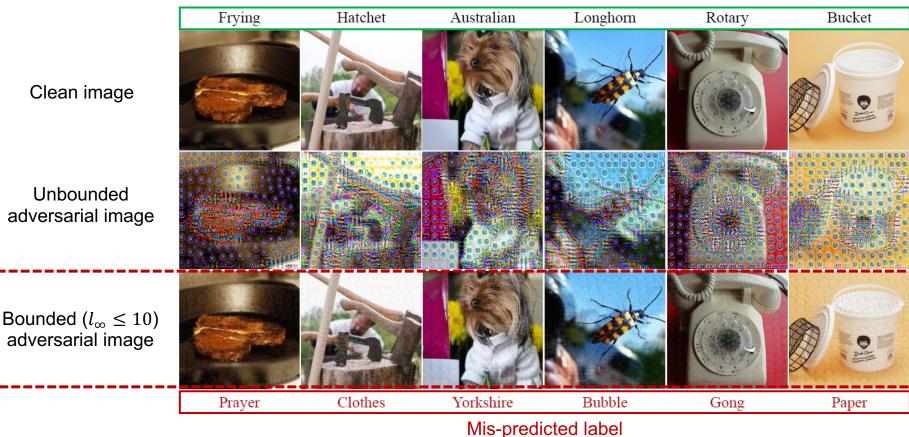
• Effect of learnable context words

Type	$\# ext{ of words}$	Text Prompt	Accuracy (\downarrow)
	M = 4	"a photo of a [class]"	46.69
	IVI - 4	"a sketch of a [class]"	47.02
Heuristic	M = 5	"a photo style of a [class]"	46.14
		"a sketch style of a [class]"	47.70
		"a $[\mathbf{V}_{rand}]$ style of a $[class]$ "	47.81
Learnable	M = 4	$``[\mathbf{V}_1][\mathbf{V}_2][\mathbf{V}_3][\mathbf{V}_4] \ [class]"$	45.44
	M = 16	$"[\mathbf{V}_1][\mathbf{V}_2]\cdots[\mathbf{V}_{16}] \ [\text{class}]"$	43.91

• Prompt learning is more effective than engineering.



Qualitative results of image classification

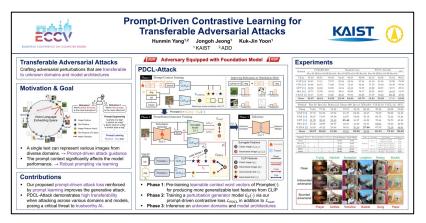


GT class label

Conclusion



- PDCL-Attack demonstrates high attack transferability across unknown domains and model architectures, posing a critical threat to trustworthy AI.
- CLIP model guidance reinforced by prompt learning in a joint vision-language space significantly enhances the attack transferability.
- We hope our work inspires further research on training robust models to defend against adversaries equipped with emerging foundation models.



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