



# Characterising Robustness via Natural Input Gradients

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Adversarial Training is SOTA but expensive (minimax)

We get >90% of the performance at 60% of the cost via gradient regularisation on ImageNet

Key ingredients for large scale: smooth activation & adaptive optimisers



## Definition of loss-input gradients

$$\nabla_x \mathcal{L} := \nabla_x \mathcal{L}_{CE}(f_\theta(x), y),$$

loss-input gradient of model  $f_\theta$  on example  $x$  with groundtruth class  $y$



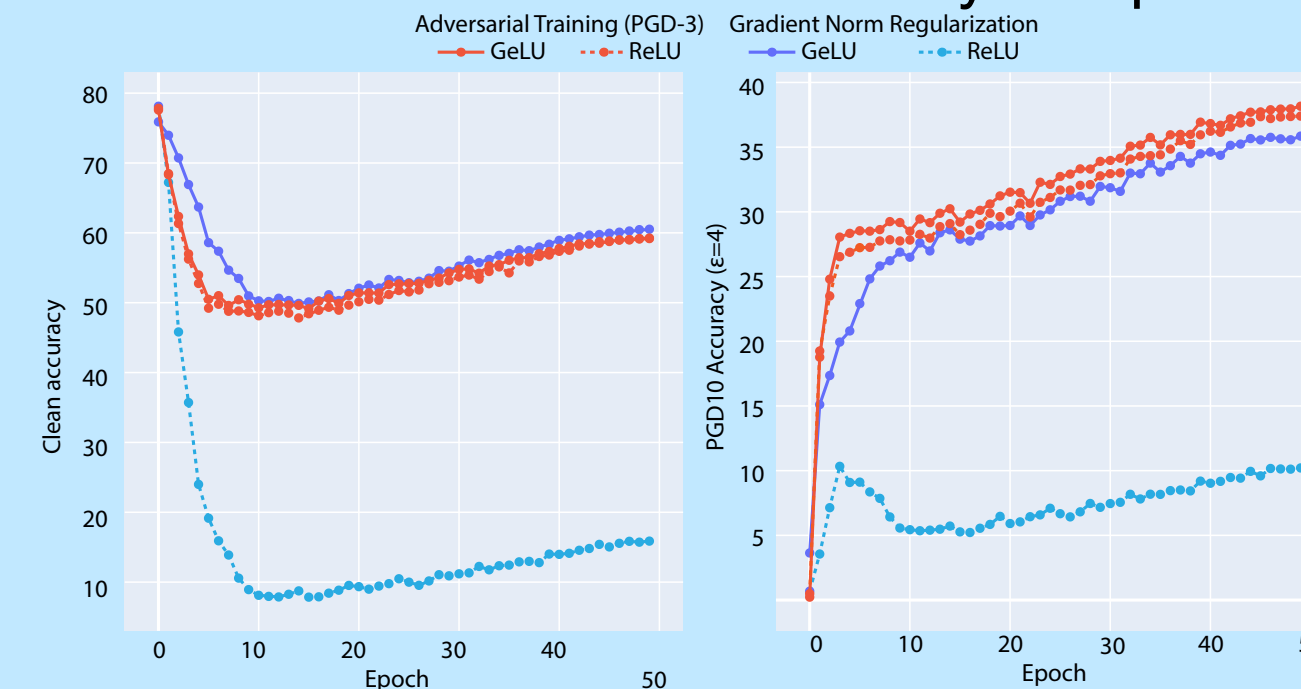
## Definition of GradNorm loss

$$\mathcal{L}_{\text{GradNorm}}(\mathbf{x}, y) = \lambda_{CE} \mathcal{L}_{CE}(f_\theta(\mathbf{x}), y) + \lambda_{GN} \frac{\epsilon}{\sigma} \|\nabla_x \mathcal{L}_{CE}(f_\theta(\mathbf{x}), y)\|_1$$

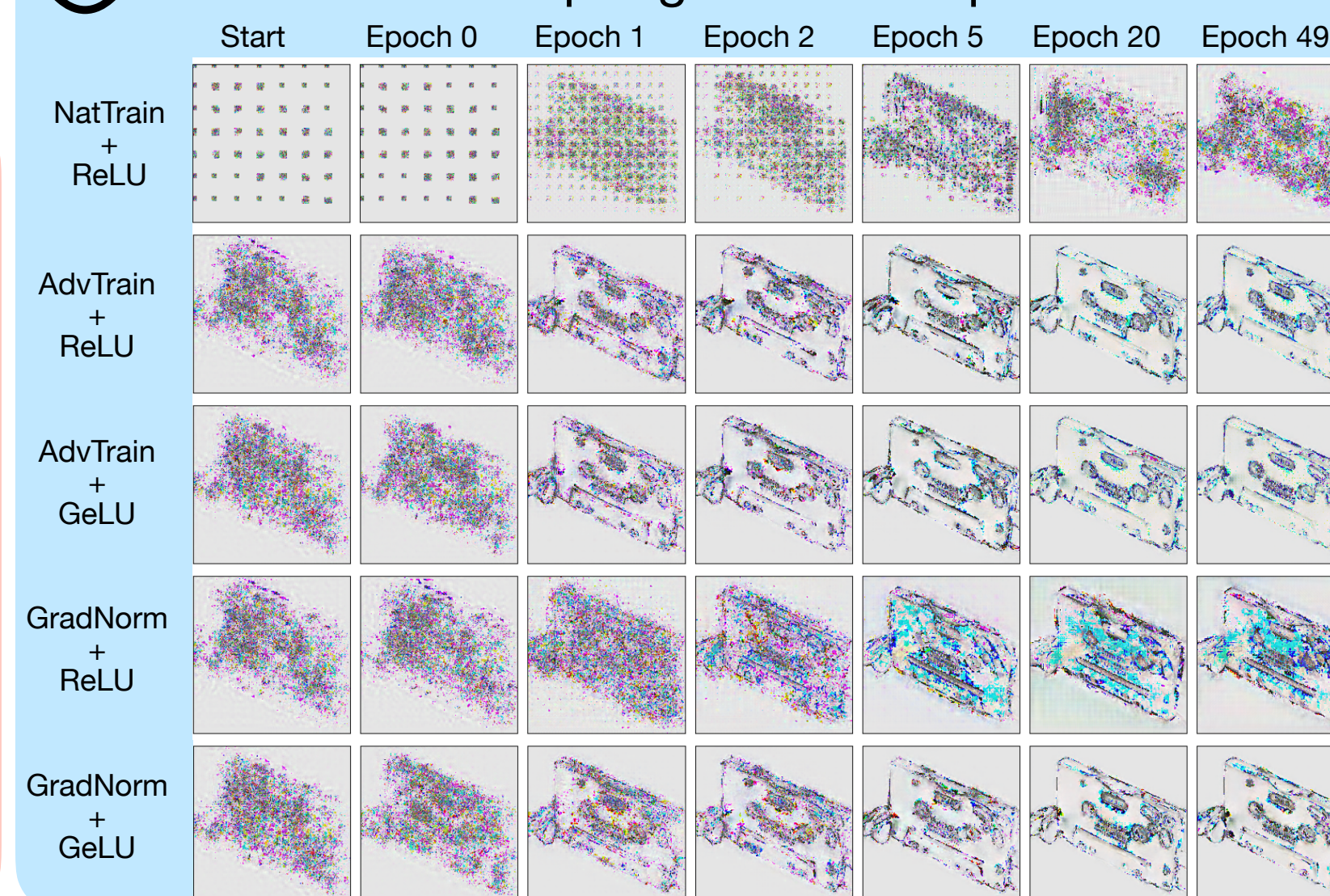
Where  $\lambda_{CE} = 0.8$ ,  $\lambda_{GN} = 1.2$ ,  $\epsilon = 4/255$ ,  $\sigma = 0.224$



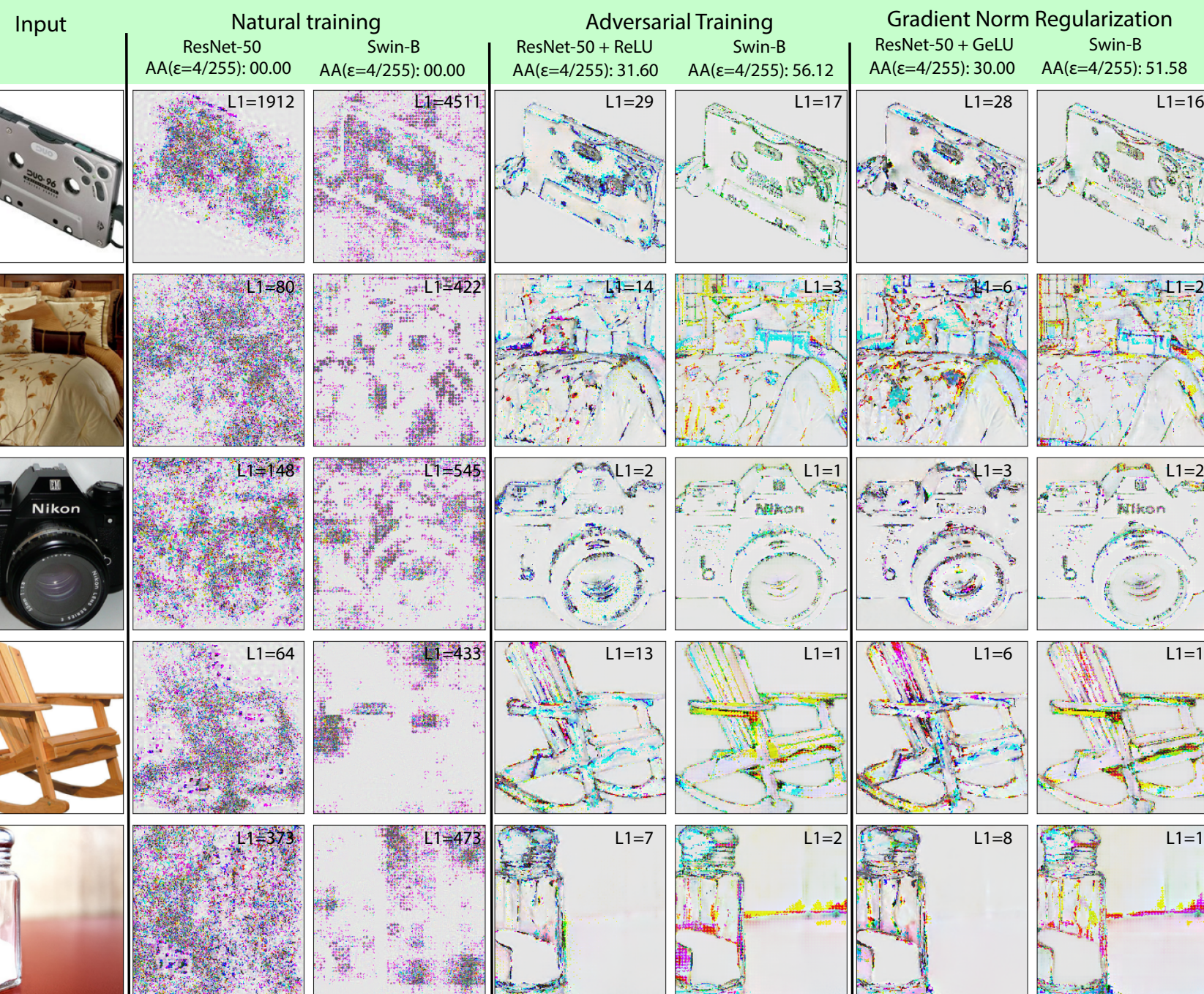
## Clean and PGD10 accuracy vs epoch



## Loss-input gradient vs epoch



## Visualisation of loss-input gradients



## Clean and AutoAttack accuracy

Method	Clean	AutoAttack- $L_\infty$		
		$\epsilon = \frac{1}{255}$	$\epsilon = \frac{2}{255}$	$\epsilon = \frac{4}{255}$
Natural Training	84.19	00.00	00.00	00.00
Grad. Norm ( $\lambda_{CE} = 0.8, \lambda_{GN} = 1.2$ )	77.78	72.04	66.20	51.58
Adv. Train. (PGD-3, $\epsilon = 4$ )	77.20	72.46	67.38	56.12



## PGD100 accuracy for $\epsilon \in [0, 32]$

