# **Lost and Found: Overcoming Detector Failures in Online Multi-Object Tracking**

**Lorenzo Vaguero**, Yihong Xu, Xavier Alameda-Pineda, Victor M. Brea, Manuel Mucientes

ECCV 2024 – The 18th European Conference on Computer Vision

1st October, 2024

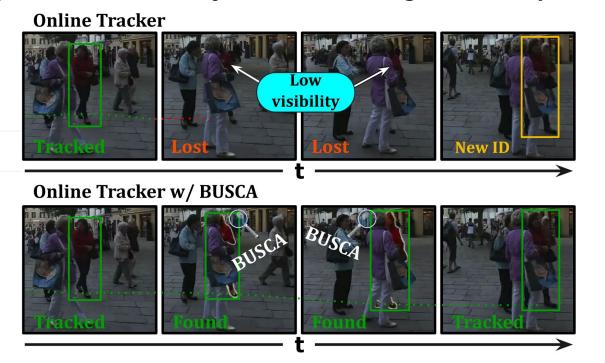






## Object detectors are not perfect

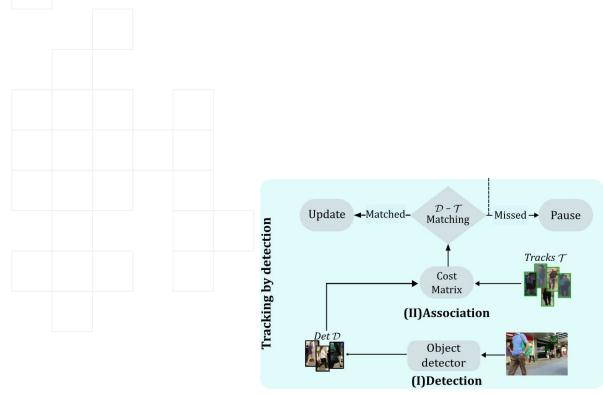
Running a **detector** on **every frame** does **not guarantee optimal** results



We want to rescue those tracks without detections

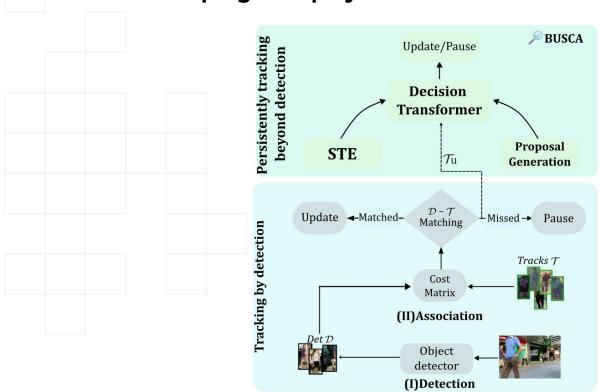
## Tracking by Detection

**TbD** trackers pause/deactivate the track if it has no matching detections



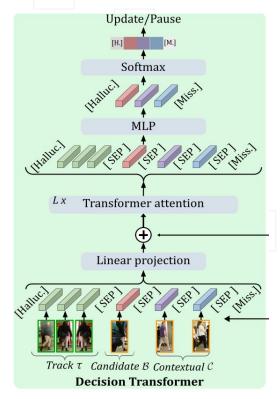
#### Building Unmatched trajectorieS Capitalizing on Attention

BUSCA is a plug-and-play module that does not rely on detections



#### Decision Transformer

We propose an online Transformer-based architecture to solve associations



**Inspired from NLP** (multi-choice question-answering)

Ouestion

What should I get for dinner if I don't like spicy food?

Answ. 1

Answ. 2

Answ. 3

Tacos

Paella

Buffalo Wings







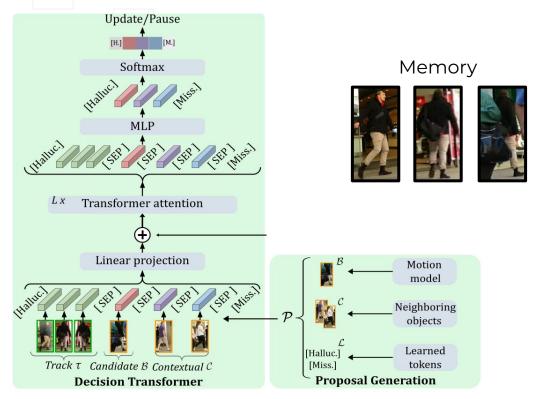


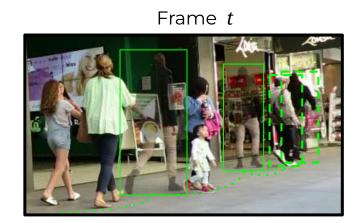




### Proposal Generation

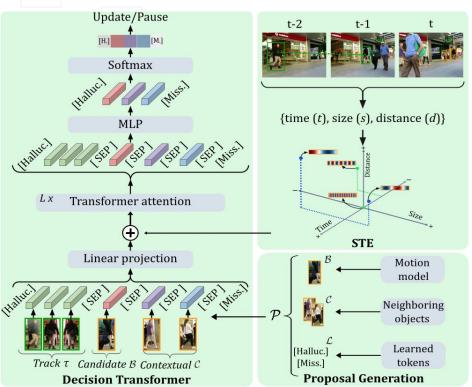
We use motion predictions, nearby objects, and learnable tokens as candidates

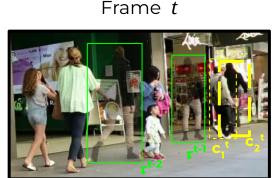


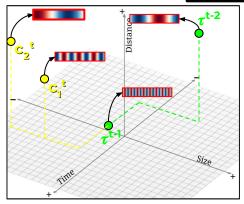


## Spatiotemporal Encoding

Spatiotemporal encoding enables relationships between motion and appearance







## Experimental results

	MOT16				MOT17				MOT20			
	MOTA↑	HOTA↑	IDF1↑	$\mathbf{IDSW} \!\!\downarrow$	MOTA↑	<b>HOTA</b> ↑	IDF1↑	$IDSW \downarrow$	MOTA↑	<b>HOTA</b> ↑	IDF1↑	IDSV
MeMOT [6]	72.6	57.4	69.7	845	72.5	56.9	69.0	2724	63.7	54.1	66.1	1938
Decode-MOT [29]	74.7	60.2	73.0	1094	73.2	59.6	72.0	3363	67.2	54.5	69.0	2805
OUTrack [31]	74.2	59.2	71.1	1328	73.5	58.7	70.2	4122	68.6	56.2	69.4	222
FairMOT [78]	75.7	61.6	75.3	621	73.7	59.3	72.3	3303	61.8	54.6	67.3	5243
SGT [23]	76.8	61.2	73.5	1276	76.3	60.6	72.4	4578	72.8	56.9	70.5	2649
CorrTracker [62]	76.6	61.0	74.3	1709	76.5	60.7	73.6	3369	65.2	11—11	69.1	518
CountingMOT [48]	77.6	62.0	75.2	1087	78.0	61.7	74.8	3453	70.2	57.0	72.4	279
CenterTrack <sup>‡</sup> [83]	69.6	_	60.7	2124	67.8	52.2	64.7	3039	45.8	31.8	36.6	629
+ BUSCA (ours)	70.4 (+0.8)	${f 55.7} \ (-)$	$69.7 \\ (+9.0)$	$egin{array}{c} {\bf 927} \ (-1197) \end{array}$	68.9 (+1.1)	$55.1 \\ (\mathbf{+2.9})$	$68.8 \\ (+4.1)$	$2817 \ (-222)$	<b>49.5</b> (+3.7)	$egin{array}{c} {\bf 44.2} \\ {\bf (+12)} \end{array}$	$58.0 \\ (\mathbf{+21})$	$137 \\ (-492$
TransCenter [70]	75.7	56.9	65.9	1717	76.2	56.6	65.5	5427	72.9	50.2	57.7	262
+ BUSCA (ours)	75.7 $(+0.0)$	$egin{array}{c} {\bf 61.9} \ (+5.0) \end{array}$	74.5 (+8.6)	${f 1038} \ (-679)$	<b>76.2</b> (+0.0)	$egin{array}{c} {\bf 61.7} \ (+{f 5.1}) \end{array}$	$74.1 \ (+8.6)$	${f 3282} \ ( ext{-2145})$	<b>73.9</b> (+1.0)	$58.8 \\ (\mathbf{+8.6})$	$72.4 \\ (+15)$	175 (-86
GHOST <sup>†</sup> [51]	78.3	63.0	77.4	709	78.7	62.8	77.1	2325	73.7	61.2	75.2	126
+ BUSCA (ours)	<b>78.5</b> (+0.2)	$f 63.2 \ (+0.2)$	77.5 (+0.1)	$707 \ (-2)$	79.0 (+0.3)	$62.9 \\ (\textbf{+0.1})$	77.0 (-0.1)	${f 2295} \ (-30)$	<b>74.2</b> (+0.5)	$61.3 \\ (\textbf{+0.1})$	$75.1 \\ (-0.1)$	125 (-13
StrongSORT <sup>†</sup> [15]	78.3	63.8	78.9	437	78.3	63.5	78.5	1446	72.2	61.5	75.9	106
+ BUSCA (ours)	78.4 (+0.1)	$64.2 \\ (+0.4)$	79.5 (+0.6)	<b>434</b> (-3)	78.6 (+0.3)	$63.9 \\ (+0.4)$	$79.2 \\ (+0.7)$	<b>1428</b> (-18)	72.7 (+0.5)	$61.8 \\ (+0.3)$	$76.3 \\ (+0.4)$	100 (-60
ByteTrack* [77]	78.2	62.8	77.2	892	78.9	62.8	77.1	2363	74.2	60.4	74.5	92
+ BUSCA (ours)	78.5 $(+0.3)$	$63.3 \\ (+0.5)$	$77.9 \\ (+0.7)$	$743 \\ (-145)$	<b>79.3</b> (+0.4)	$63.1 \\ (+0.3)$	$77.7 \\ (+0.6)$	$2358 \ (-5)$	74.5 (+0.3)	$60.5 \\ (+0.1)$	74.4 $(-0.1)$	<b>920</b> (-5

## Any questions?

See you on Tuesday, October 1st at Session 1

Poster #248

Lost and Found: Overcoming Detector Failures in Online Multi-Object Tracking

**Lorenzo Vaguero**, Yihong Xu, Xavier Alameda-Pineda, Victor M. Brea, Manuel Mucientes





