



YOLOv9: Learning What You Want to Learn Using Programmable Gradient Information

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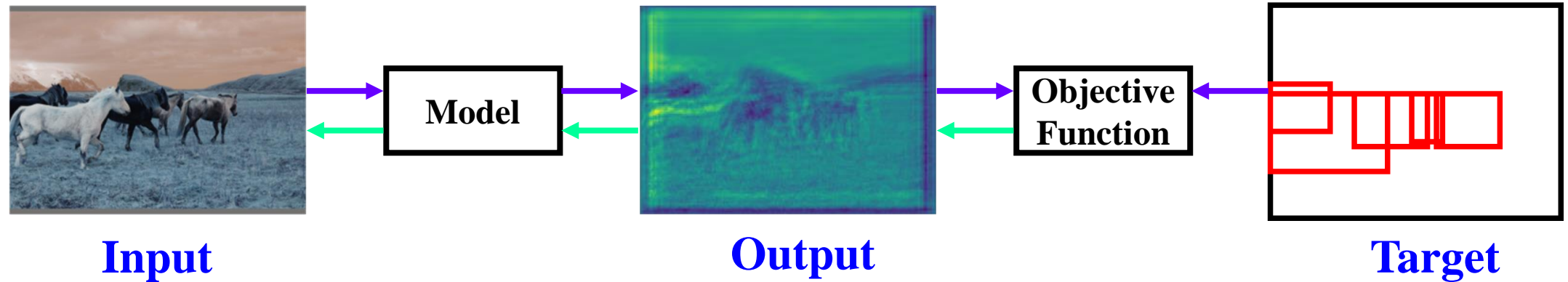
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Poster: TUE-AM-Session1

Motivation (1/3)

- **YOLOv4 to YOLOv7 learn diverse and consistent features through back-propagated gradient flow.**



← YOLOv4 to YOLOv7: Optimize gradient path.

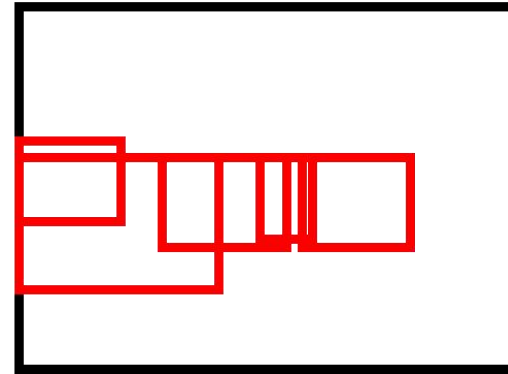
↔ YOLOv9: Optimize both forward path and gradient path.

- **In YOLOv9, deal with the information bottleneck problem.**

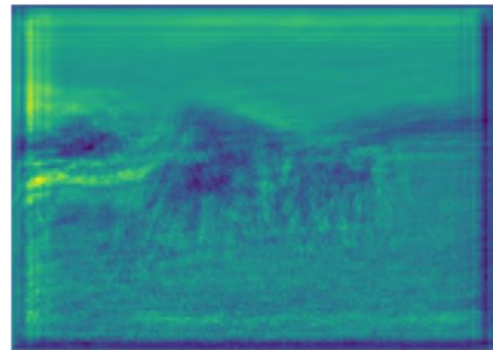
Motivation (2/3)

Information Bottleneck of DNNs:

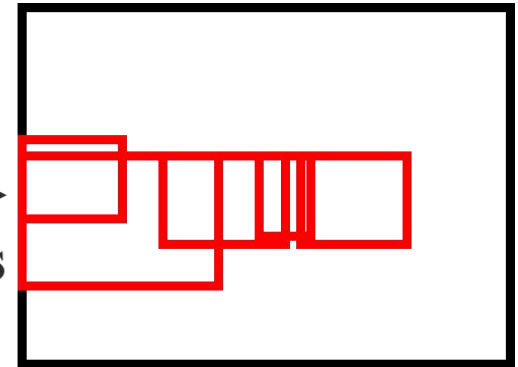
$$I(\mathbf{x}; \mathbf{x}) \geq I(\mathbf{x}; f_0(\mathbf{x})) \geq I(\mathbf{x}; f_1(f_0(\mathbf{x}))) \geq \dots \geq I(\mathbf{x}; F_\theta(\mathbf{x}))$$



50 Layer
PlainNet


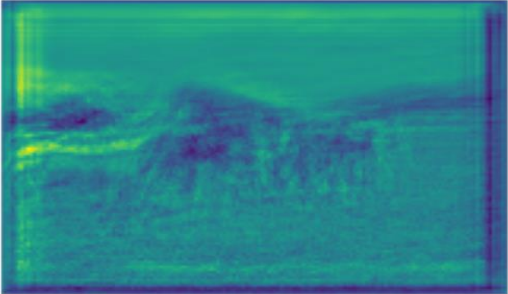
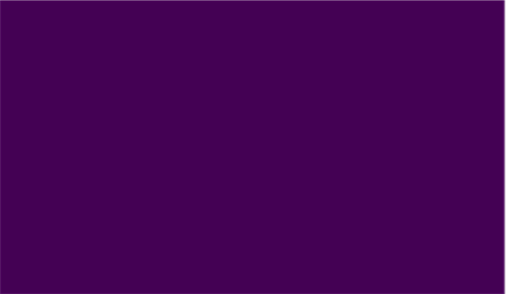

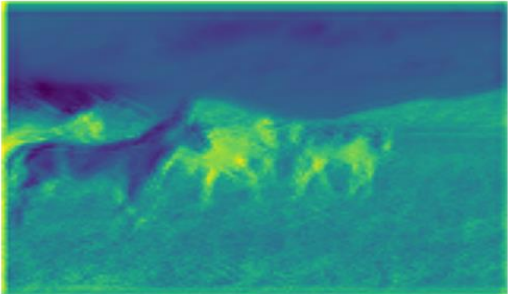
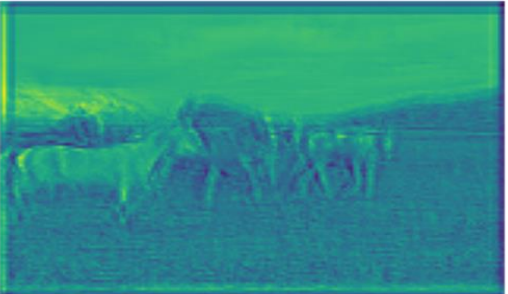
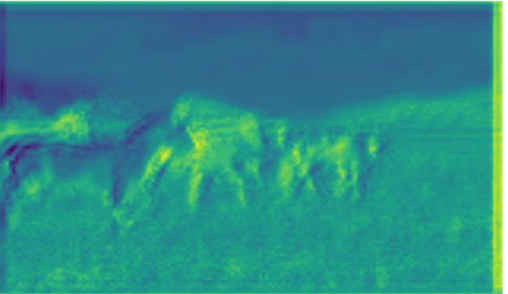



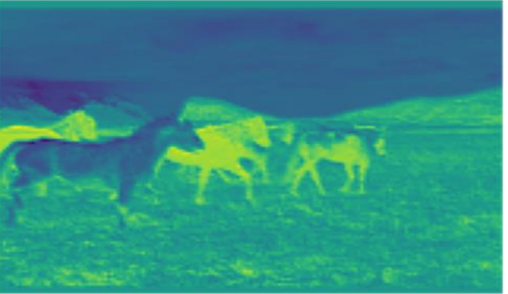


Loss



Motivation (3/3)

Data loss in different object detection models at different depths

	Input Image	50 Layers	100 Layers	150 Layers
PlainNet				
ResNet				
GELAN				

Mainstream Approaches to Solving Information Bottleneck Problems

- *Reversible architectures*

 - pros: output data can be restored to input data through reverse calculations*

 - cons: need extra layers, thus increase inference cost*

- *Masked modeling*

 - pros: use reconstruction loss to preserve input information*

 - cons: reconstruction loss may contradict with target loss*

- *Deep supervision*

 - pros: add prediction heads in shallow layers*

 - cons: if shallow supervision loses information during training, it will cause considerable error accumulations*

Our solutions for information bottleneck

- The design of **PGI** (**P**rogrammable **G**radient **I**nformation)
 - reversible architecture + deep supervision
- The design of **GELAN** (**G**eneralized **E**fficient **L**ayer **A**ggregation **N**etwork)

The Design of PGI (1/3)

- Use **auxiliary reversible branch** to make information remains intact when forwarded to the network end
- Use **multi-level auxiliary information** to help learn unbiased information
- Both techniques can be classified as **bag-of-freebies**

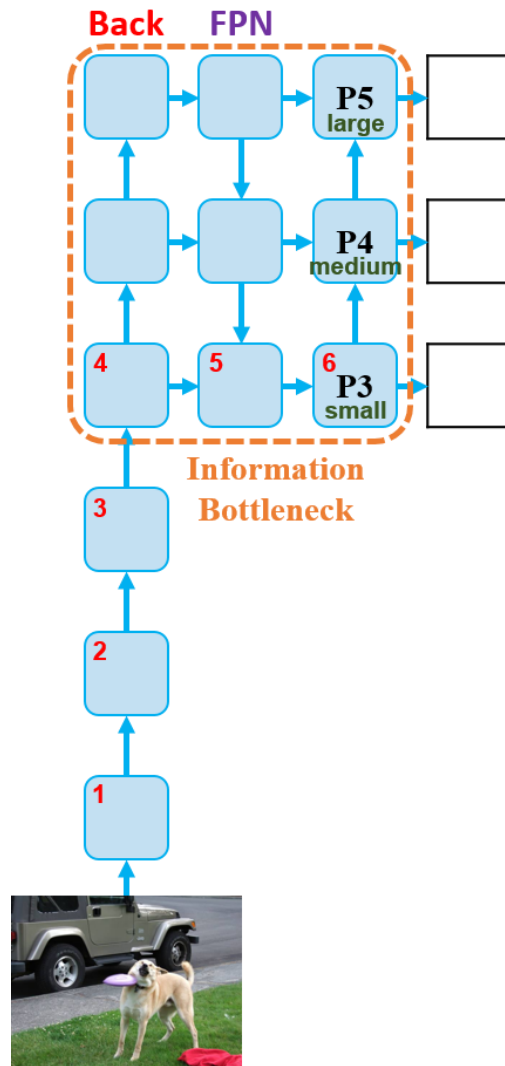
Bag-of-freebies

1. Improve accuracy
2. May increase training cost
3. No additional inference cost

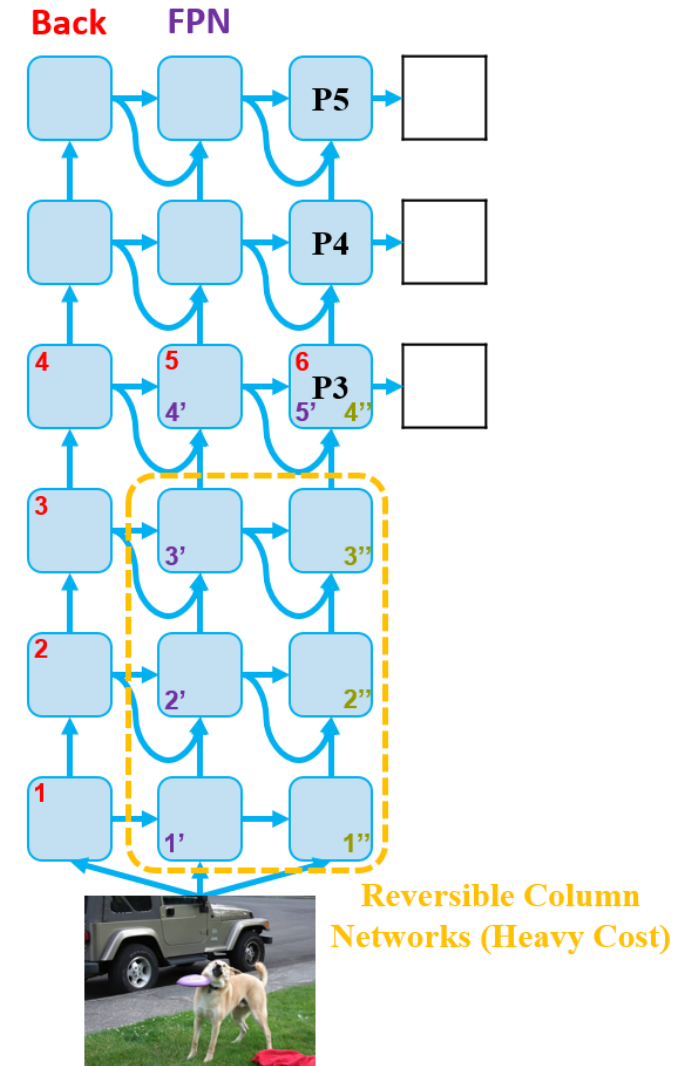


The Design of PGI (2/3)

**PGI: Reversible
Architecture
+ Deep Supervision**

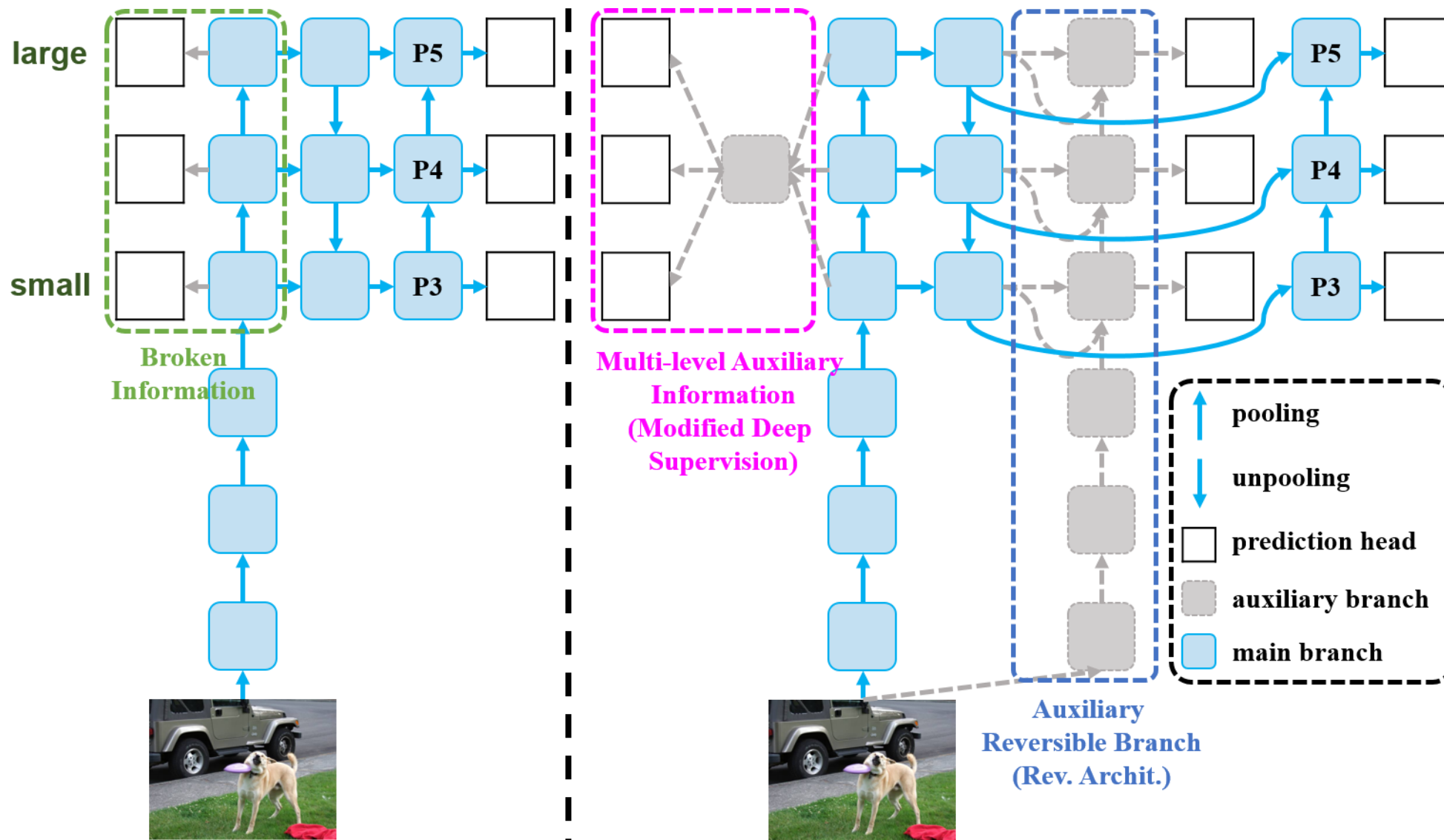


(a) PAN [37]



(b) RevCol [3]

The Design of PGI (3/3)



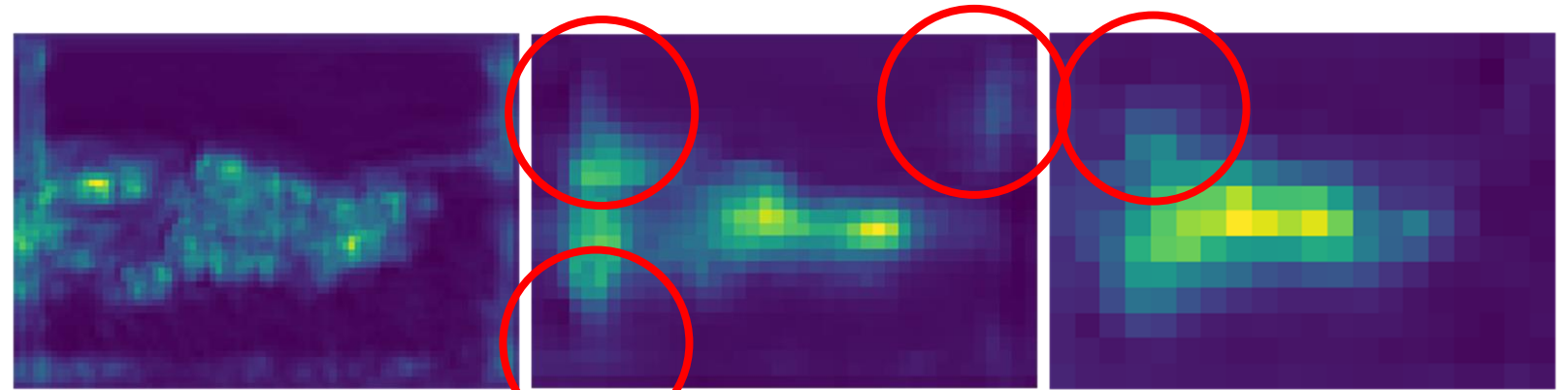
(c) Deep Supervision

(d) Programmable Gradient Information

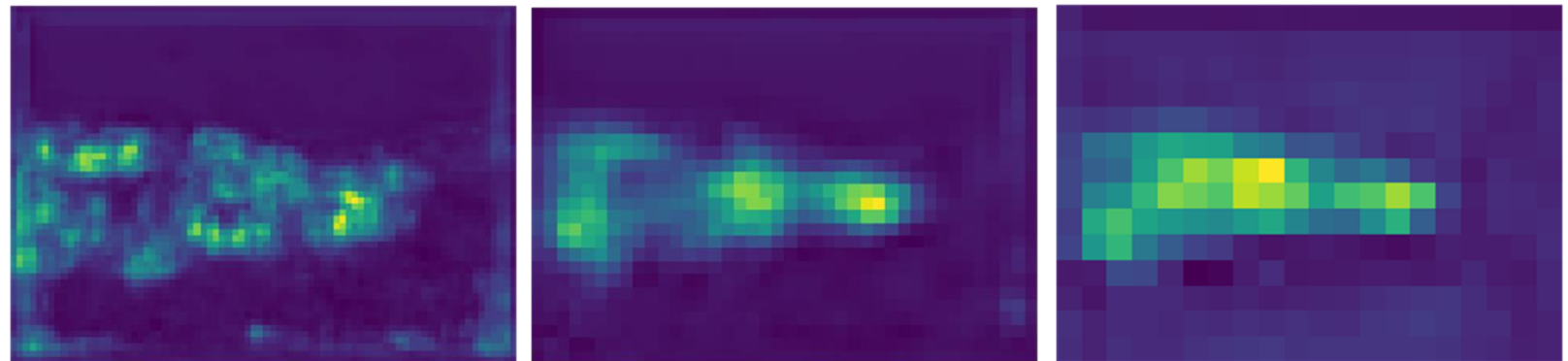
The Power of PGI

Power of PGI (1/3)

Visualize features of warm-up model on object detection task



Warm up features without PGI



Warm up features with PGI

Power of PGI (2/3)

PGI solves the problem of Deep Supervision (DS).

Model	Param. (M)	FLOPs (G)	AP (%)
GELAN-S	7.1	26.4	46.7
+ DS	-	-	46.5 (-0.2)
+ PGI	-	-	46.8 (+0.1)
GELAN-C	25.3	102.1	52.5
+ DS	-	-	52.5 (=)
+ PGI	-	-	53.0 (+0.5)
GELAN-E	57.3	189.0	55.0
+ DS	-	-	55.3 (+0.3)
+ PGI	-	-	55.6 (+0.6)

Power of PGI (3/3)

PGI can be generalized to various models, tasks, and training scheme

Generalize to model scales

COCO det	YOLOv9-S	YOLOv9-M	YOLOv9-L	YOLOv9-E
#parameter	7.1M	20.0M	25.3M	57.3M
without PGI	46.7	51.1	52.5	55.0
with PGI	46.8	51.4	53.0	55.6

Generalize to various tasks

Multi-task	Detection	Segment	Panoptic	Caption
metric	AP ^{box}	AP ^{box} /AP ^{seg}	mIoU/PQ	BLEU4
without PGI	52.5	52.3/42.4	39.0/39.4	38.8
with PGI	53.0	52.9/43.2	39.8/40.5	39.1

Generalize to small dataset

VOC det	YOLOv9-S	YOLOv9-S	YOLOv8-S	YOLOv8-L
pretrain	-	COCO (PGI)	COCO	COCO
without PGI	64.4	73.5	67.1	73.8
with PGI	65.1	74.4	-	-

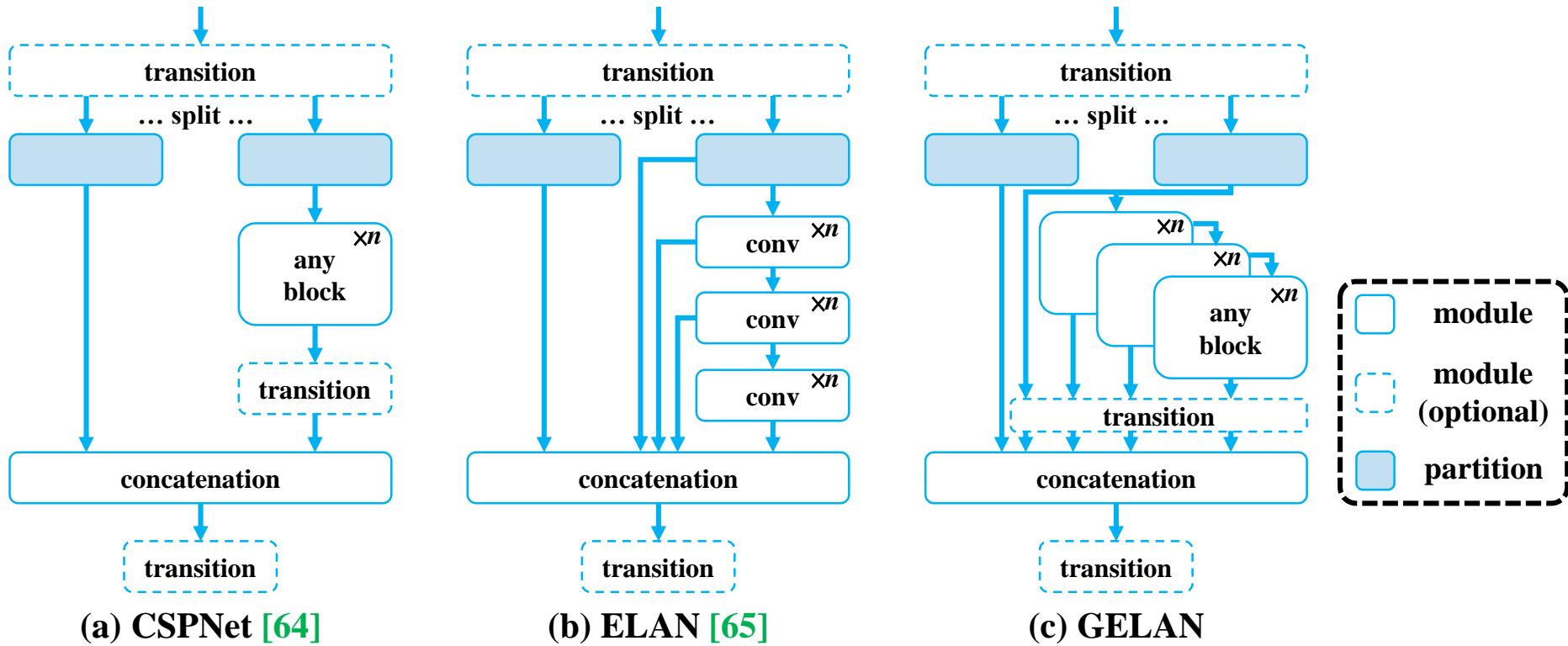
Design of GELAN: Generalized Efficient Layer Aggregation Network (1/2)

GELAN = **CSPNet** [[Wang et al. 2019](#)]
+ **ELAN** [[Wang et al. 2022](#)]

Characteristics of GELAN

1. compatible to various existing modern networks
2. has extremely high parameter utilization
3. has excellent inference speed on various devices

Design of GELAN: Generalized Efficient Layer Aggregation Network (2/2)



Power of GELAN

Power of GELAN

GELAN can be generalized to various models and has high inference speed

	MG YOLOv9	LH YOLOv9	YOLOv9 TR	YOLOv9 Lite	YOLOv9 Light
#Parameter	25.3M	21.1M	14.1M	13.3M	2.5M
FLOPs	102.1G	82.5G	67.5G	66.7G	11.0G
mAP	53.3%	52.9%	53.1%	52.7%	44.1%

Generalize to various models: mask-guided YOLOv9 (MG YOLOv9), light head YOLOv9 (LH YOLOv9), YOLOv9 with Transformer (YOLOv9 TR), YOLOv9 using hybrid convolution (YOLOv9 Lite), and YOLOv9 using depth-wise convolution (YOLOv9 Light).

	YOLOv6-L 3.0	YOLOv7 AF	YOLOv8-L	YOLOv9-C	YOLOv9-C-TR
Latency	7.9ms	6.7ms	8.1ms	6.1ms	5.9ms
mAP	51.8/52.8 ^{distill}	53.0	52.9	53.0	53.1

GELAN has very high inference speed, it about 25% faster than YOLOv8.

Results

Results

YOLOv9 has strong ability on multi-task applications

PGI makes YOLOv9 outperforms SOTA methods in all aspects.

ECCV'24
(Oral)

Model	#Param.	AP ^{box}	AP ^{mask}	mIoU ^{sem}	mIoU ^{stuff}	PQ ^{pan}	BLEU4 ^{cap}	Acc ^{gnd}
GiT-B	131M	46.7	31.9	47.8*	-	-	35.4 ⁺	85.8
GiT-L	387M	51.3	35.1	50.6*	-	-	35.7 ⁺	88.4
GiT-H	756M	52.9	35.8	52.4*	-	-	36.2 ⁺	89.2
YOLOv9	45.5M	52.2	42.9	49.4	56.8	42.2	39.4	-

17x lighter

ECCV'24
(Oral)

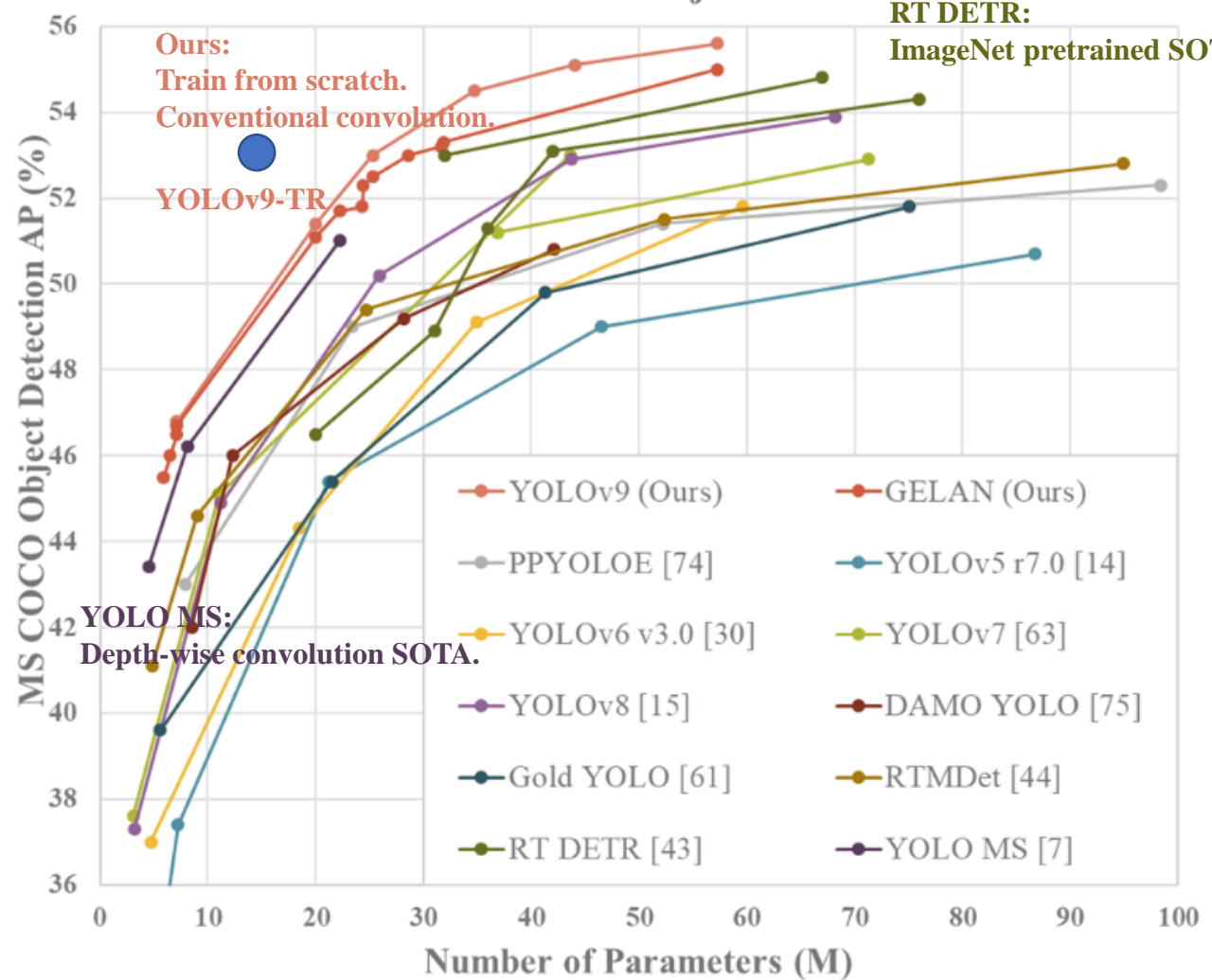
Model	Time ^{total}	Time ^{box}	Time ^{mask}	Time ^{sem}	Time ^{stuff}	Time ^{pan}	Time ^{cap}	Time ^{gnd}
GiT-B	2589ms	359	1149	717	-	-	272	92
GiT-L	5320ms	689	2451	1617	-	-	424	139
GiT-H	8321ms	1053	3838	2703	-	-	550	177
YOLOv9	61.5ms	61.5						-

135x faster

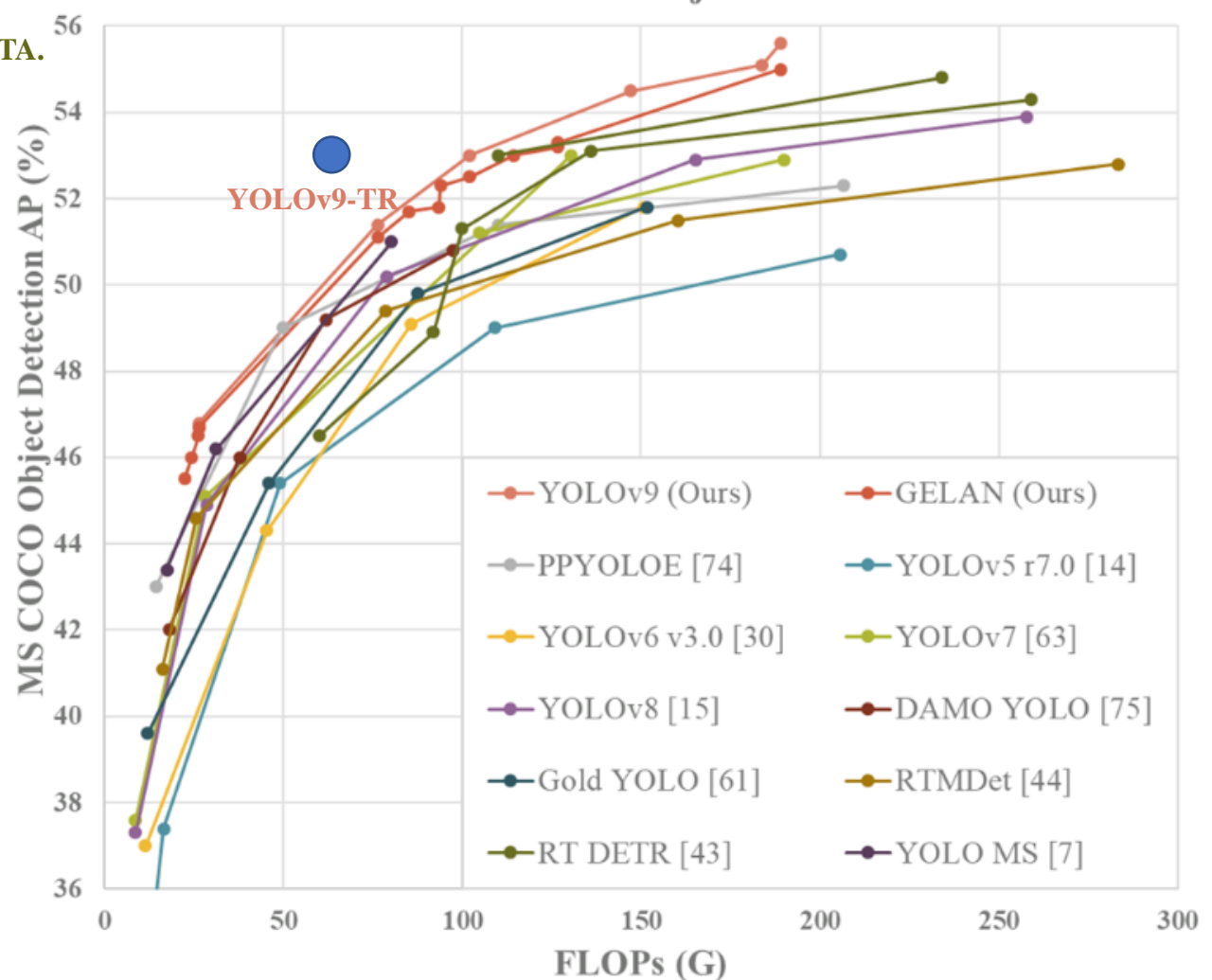
YOLOv9 gets all predictions in one shot inference

Results

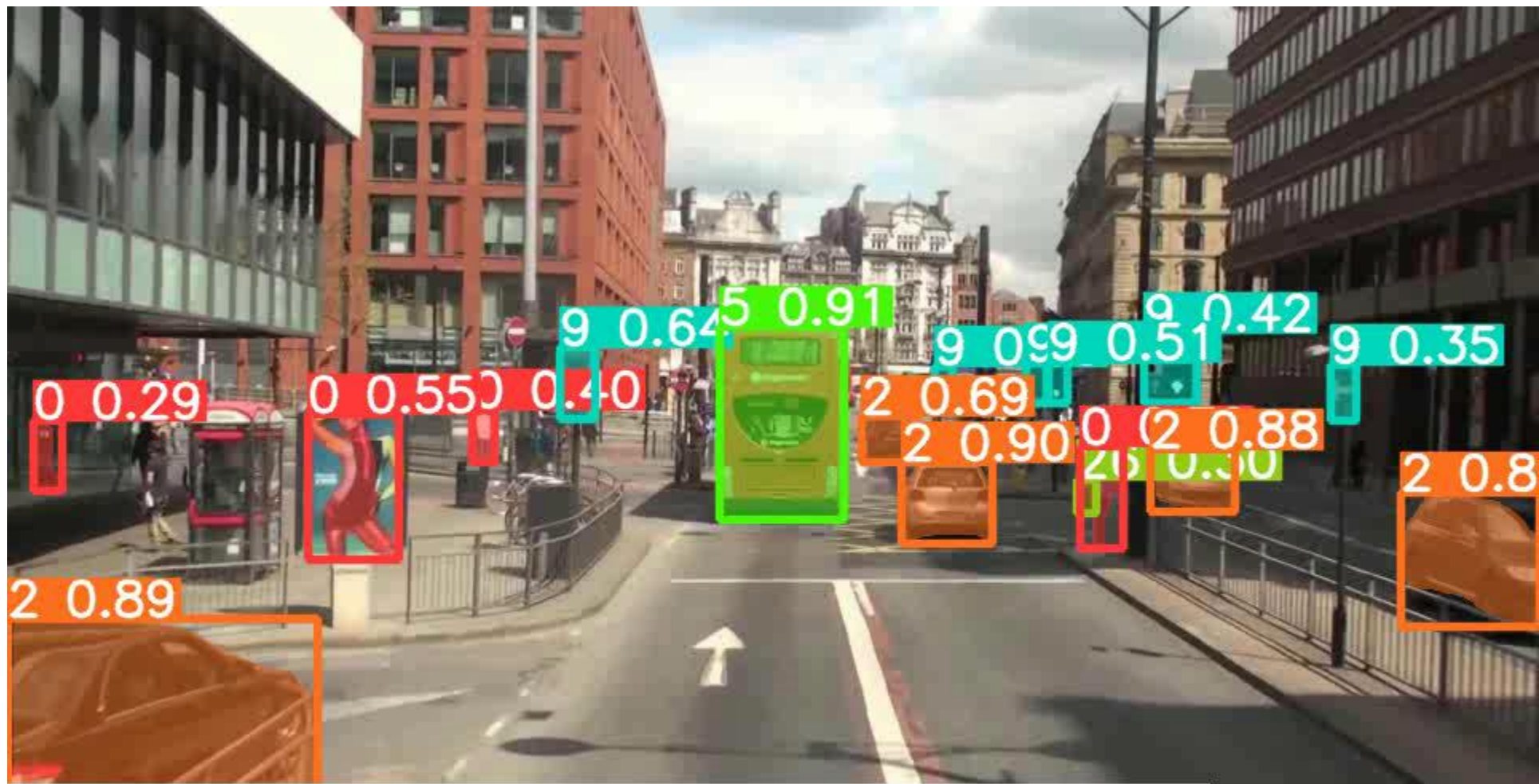
Performance on MS COCO Object Detection Dataset



Performance on MS COCO Object Detection Dataset



Generalist YOLO



A red double decker bus driving down a street

Conclusions

- **propose a trustworthy AI technology to make a model generate and learn from reliable gradient information**
- **design an efficient networks which is generalized various architectures and has low inference latency.**
- **3. show the proposed trustworthy AI technology is generalized to various models, tasks, and training scheme.**
- **4. show the proposed framework will bring real-time computer vision systems to a new achievement.**

Thanks

Q&A