



电子科技大学

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# Superpixel-informed Implicit Neural Representation for Multi-Dimensional Data



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## Background & Motivation

Implicit Neural Representation (INR) (sometimes also called coordinate-based representation) is a new way to **parameterize various signals**.

- Traditional signal representations are usually discrete, while INR parameterizes the signal as a continuous function that maps the domain of the signal to the value of the attribute at that coordinate.

Image

$$\mathbb{R}^2 \rightarrow \mathbb{R}^3, f(x, y) = (r, g, b)$$

Video

$$\mathbb{R}^3 \rightarrow \mathbb{R}^3, f(x, y, t) = (r, g, b)$$

Pixel

$$\mathbb{R}^3 \rightarrow [0, 1], f(x, y, z) = p \in [0, 1]$$

The neural network architecture [1] for INRs:

$$\Phi(\mathbf{x}) = \mathbf{W}_n (\phi_{n-1} \circ \phi_{n-2} \circ \dots \circ \phi_0)(\mathbf{x}) + \mathbf{b}_n, \quad \mathbf{x}_i \mapsto \phi_i(\mathbf{x}_i) = \sin(\mathbf{W}_i \mathbf{x}_i + \mathbf{b}_i).$$

## Experiments

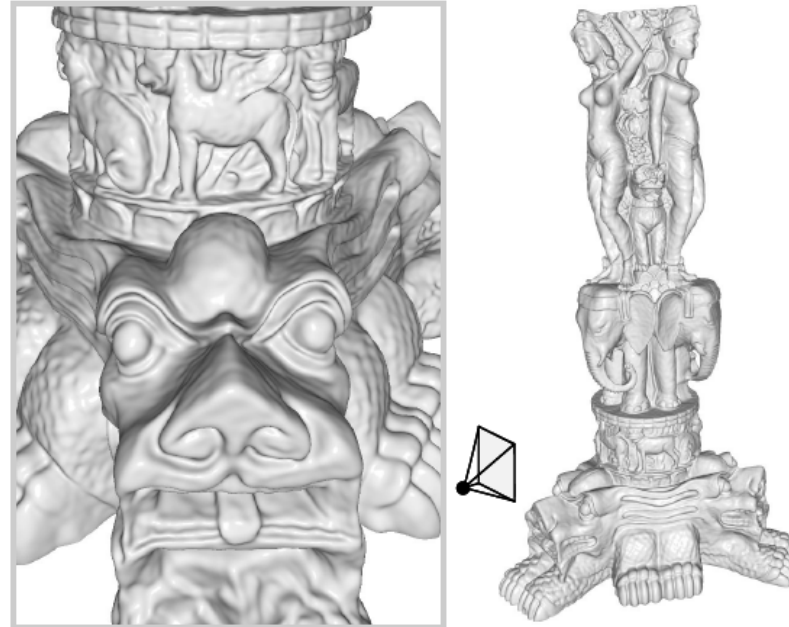
## Discussions

## Background & Motivation

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Point Cloud



Image



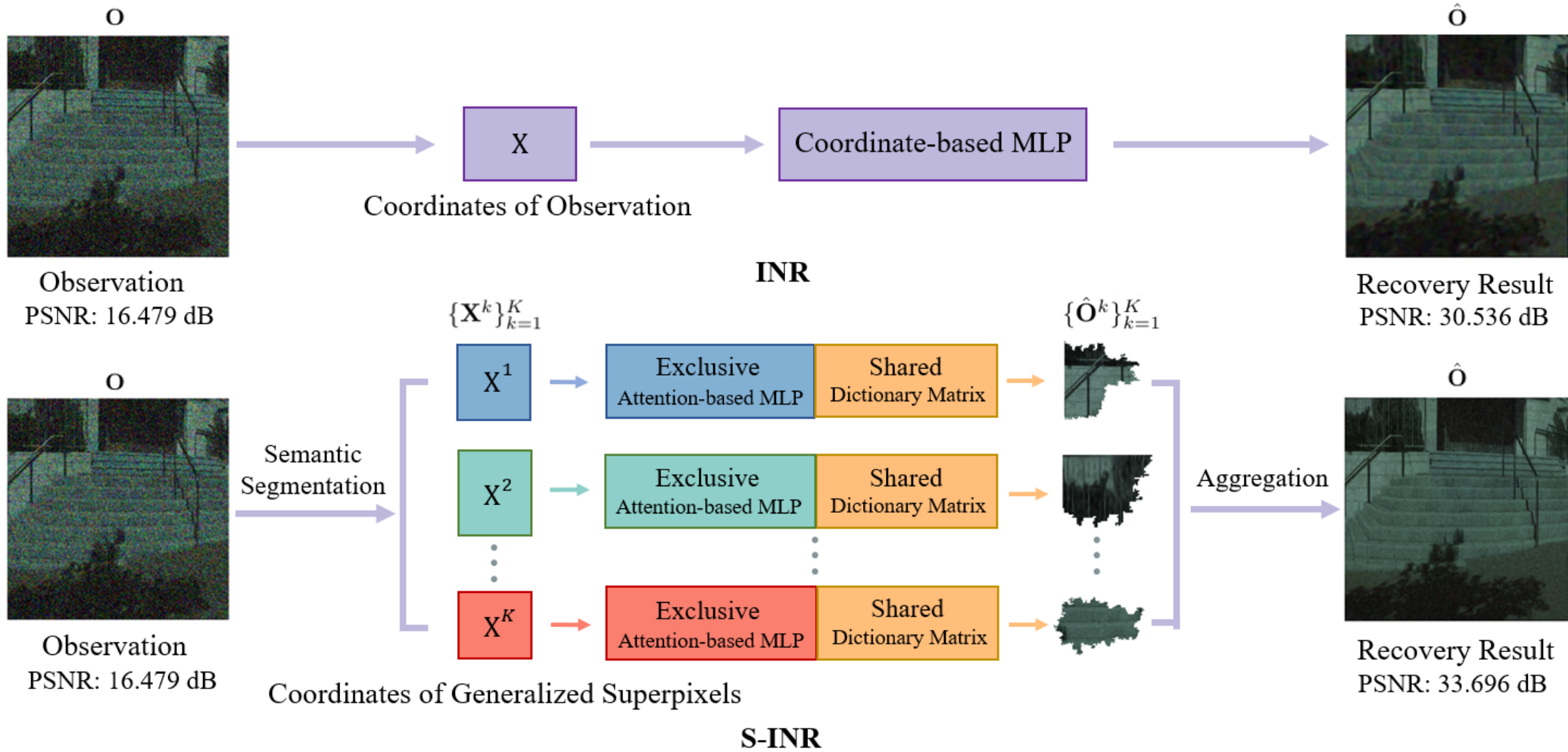
INRs have potential in multi-dimensional data recovery.

[1]Sitzmann, V., Martel, J., Bergman, A., Lindell, D., Wetzstein, G.: Implicit neural representations with periodic activation functions. Proceedings of the International Conference on Neural Information Processing Systems, NeurIPS, 2020.

## Limitations of Traditional INRs

- **Simple Mapping:** Traditional INRs map spatial coordinates to corresponding values using Multi-Layer Perceptrons (MLPs).
- **Lack of Semantic Understanding:** These methods often treat the data as a collection of points in space, ignoring the rich semantic information inherent in the data.
- **Consequences:** As a result, traditional INRs may fail to effectively capture and represent complex structures and meaningful patterns, leading to suboptimal data representation.

To leverage semantic priors from the data, we propose a novel Superpixel-informed INR (S-INR).

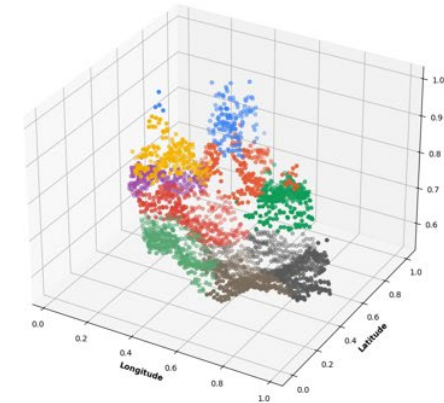




(a) Image data

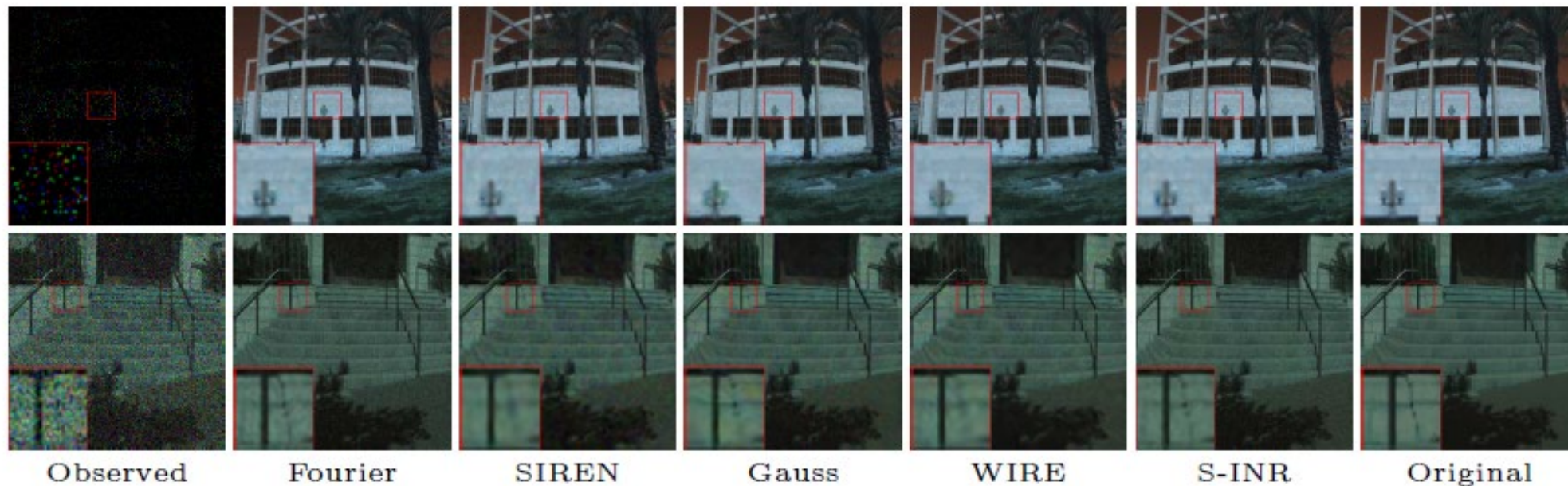


(b) 3D surface data



(c) Weather data

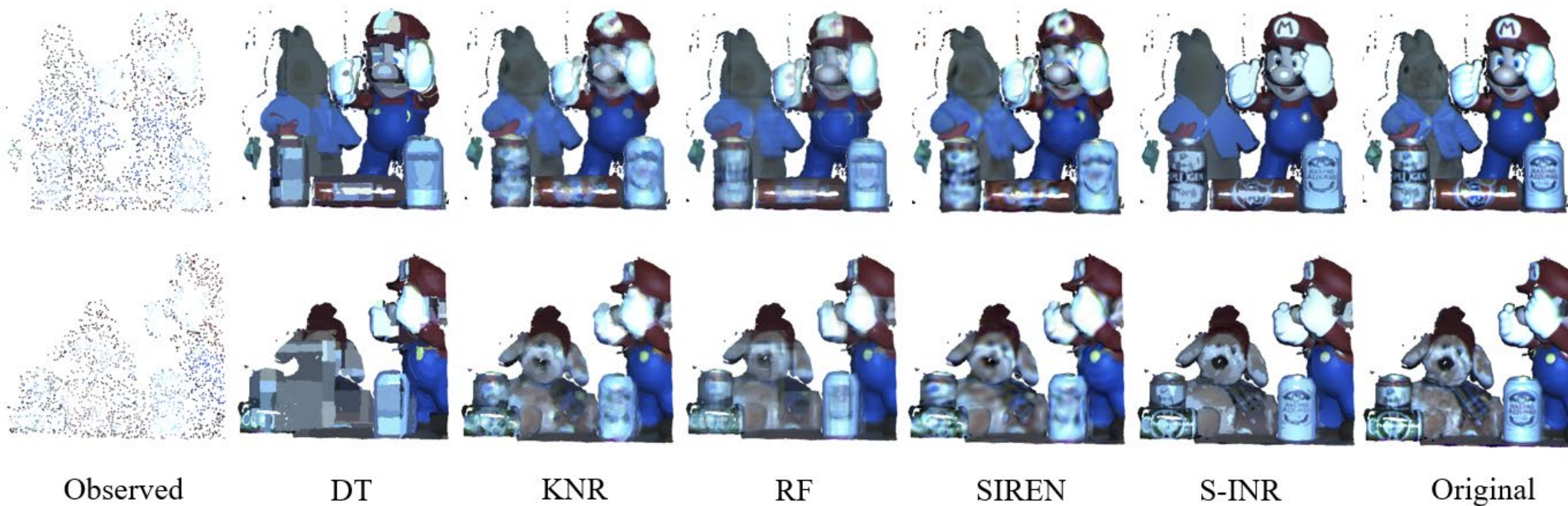
The segmentation results by our Generalized Superpixel Segmentation Algorithm (GSSA).



The results of image completion and image denoising recovery

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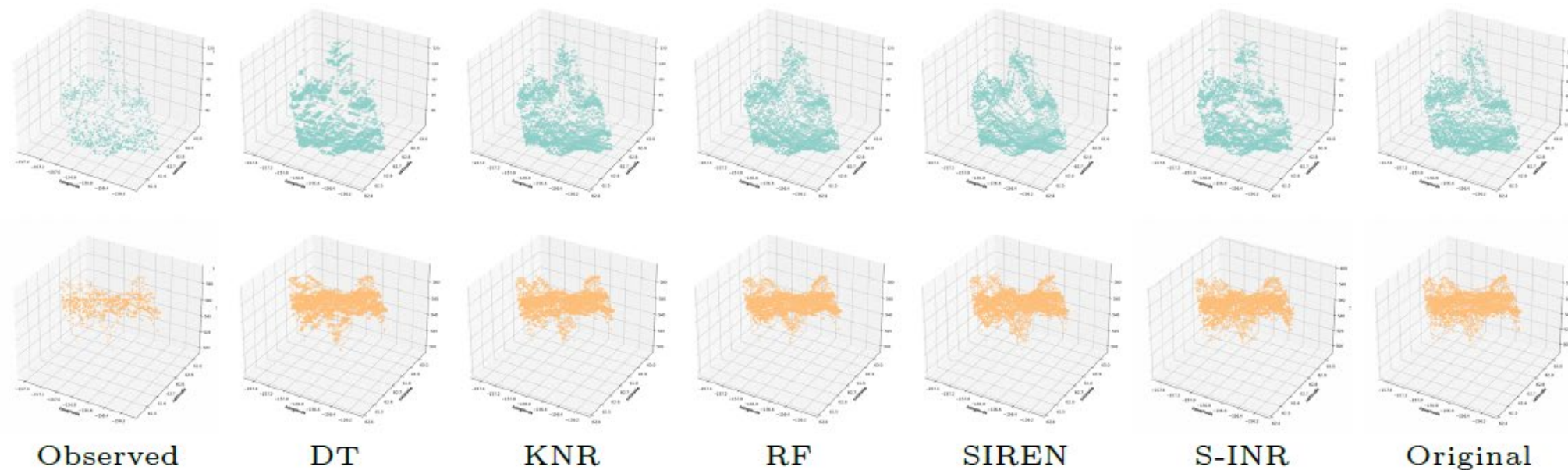
The results of 3D surface completion recovery

Discussions



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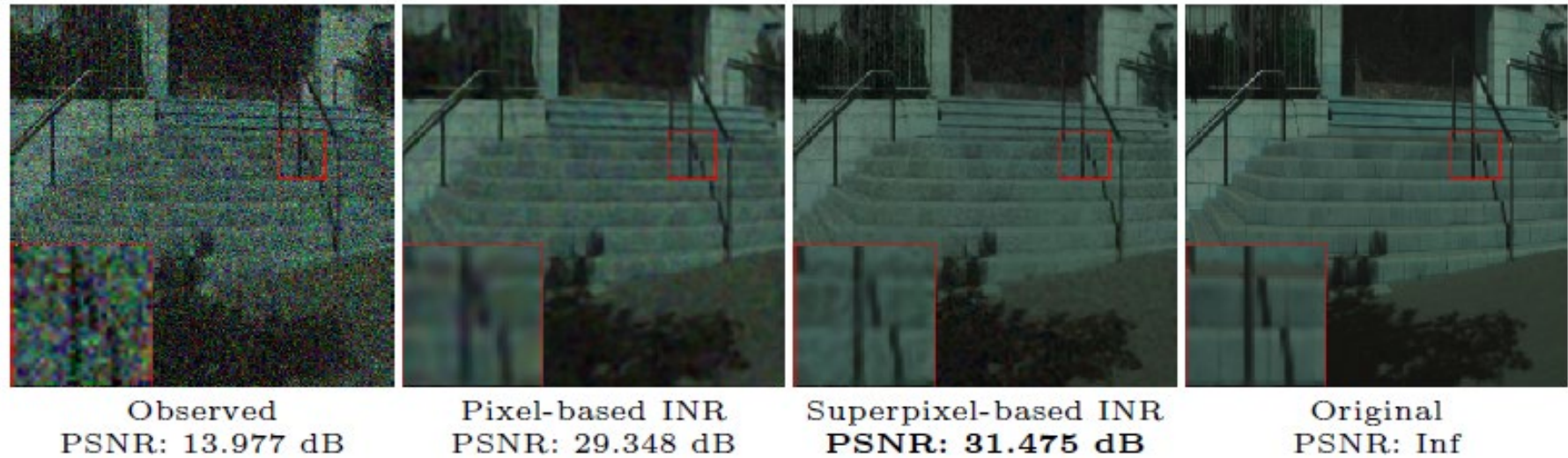
Experiments



The results of weather data completion recovery

Discussions

## Comparison of Basic Units: Pixels vs. Generalized Superpixels



The results of image denoising recovery by pixel-based INR [1] and superpixel-based INR

## Background & Motivation

## Experiments

Components			<i>Lehvim</i>		Parameters (Mb)
Generalized Superpixels	Exclusive MLPs	Shared Dictionary Matrix	PSNR	SSIM	
X	X	X	29.348	0.745	0.786
✓	X	X	31.475	0.817	<b>0.741</b>
✓	X	✓	31.997	0.818	0.797
✓	✓	X	31.012	0.787	0.902
✓	✓	✓	<b>32.394</b>	<b>0.831</b>	0.995

The quantitative results of image denoising recovery comparisons with different components in S-INR.

## Discussions



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Thanks for your listening!